

GRAIL

Gravity
Recovery
and
Interior
Laboratory

GRAIL Mission Overview

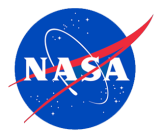
Mission Design and Navigation

Ralph B. Roncoli

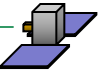
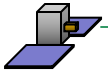
representing the work of the GRAIL Mission Design and Navigation Teams

Jet Propulsion Laboratory
California Institute of Technology
Pasadena, California

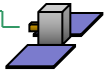
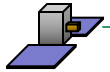
November 19, 2019
Johnson Space Center
Houston, Texas



Outline



- Mission Overview
 - Mission Timeline / Mission Phases
 - Trajectory Design Challenges
 - Trans-Lunar Cruise Trajectory Design
 - Trajectory Design Challenges in the Extended Mission
 - Maintaining a Low-Altitude Orbit about the Moon
 - Trajectory Design Challenges in the End Game
 - Designing the Final Maneuvers
 - Mission and Navigation Operations
 - Maneuver and Orbit Determination Planning
 - Contingency Planning during the TLC Phase
 - TCM Planning
- Backup Slides
 - References
 - Trans-Lunar Cruise Trajectory Characteristics
 - Maneuver Strategy for the Transition to Science Formation Phase



■ NASA Discovery Program

- Gravity Recovery and Interior Laboratory (GRAIL) mission selected in December 2007

■ Science Objectives

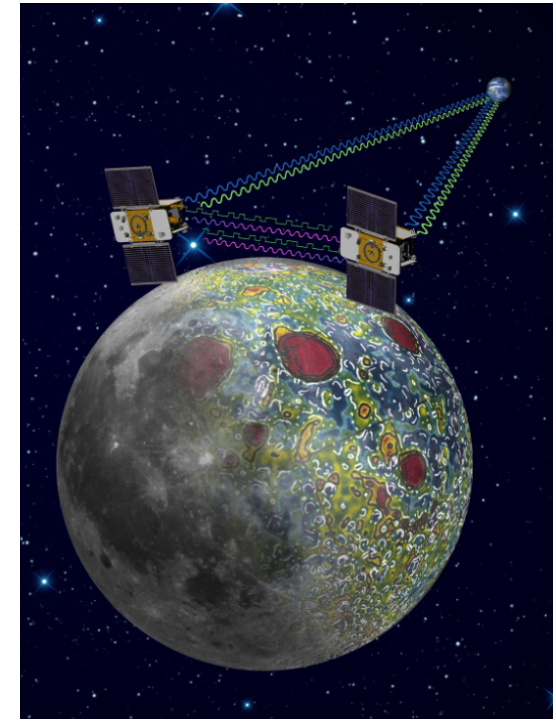
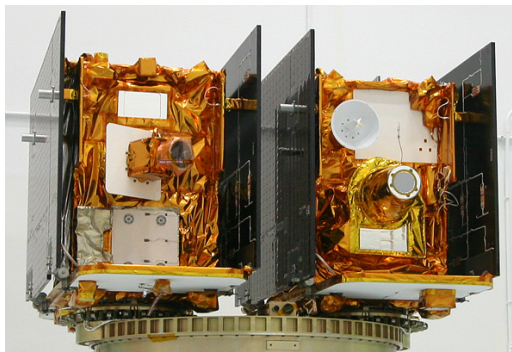
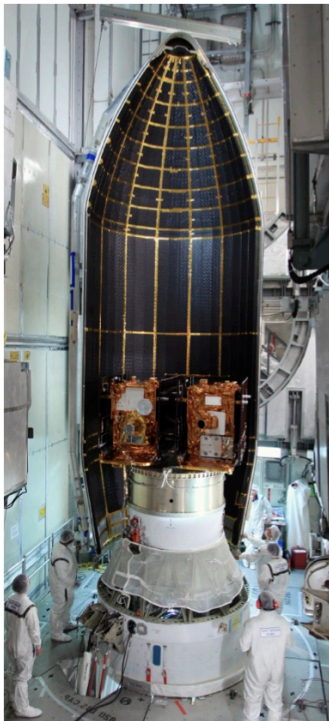
- Determine the structure and interior of the Moon by precisely measuring the distance between two orbiters and tracking their position around the Moon
- Map the global lunar gravity field to unprecedented accuracy and resolution

■ Mission Management

- JPL: Project Management / Payload
 - Includes Mission Design and Navigation
- Lockheed Martin: Spacecraft Development

■ Mission Operations

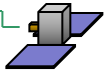
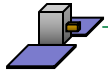
- Jointly operated by JPL and LM
 - Benefited from extensive heritage from previous JPL/LM planetary missions and operational heritage from the GRACE mission



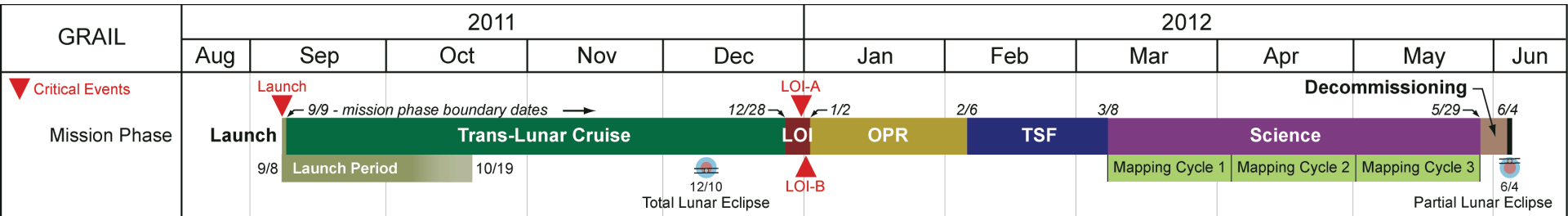


Mission Timeline / Mission Phases

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Primary GRAIL Mission



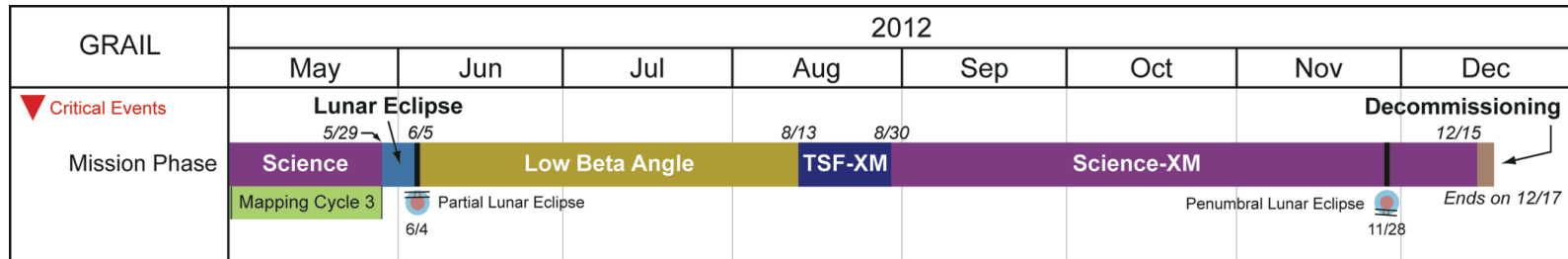
Mission Phases for Primary Mission

- 1) Launch Phase
- 2) Trans-Lunar Cruise (TLC) Phase
- 3) Lunar Orbit Insertion (LOI) Phase
- 4) Orbit Period Reduction (OPR) Phase
- 5) Transition to Science Formation (TSF) Phase
- 6) Science Phase
- 7) Decommissioning Phase

Mission Phases for Extended Mission

- 1) Lunar Eclipse (LEC) Phase
- 2) Low Beta Angle (LBA) Phase
- 3) Transition to Science Formation-XM (TSF-XM) Phase
- 4) Science-XM Phase
- 5) Decommissioning Phase

Extended GRAIL Mission

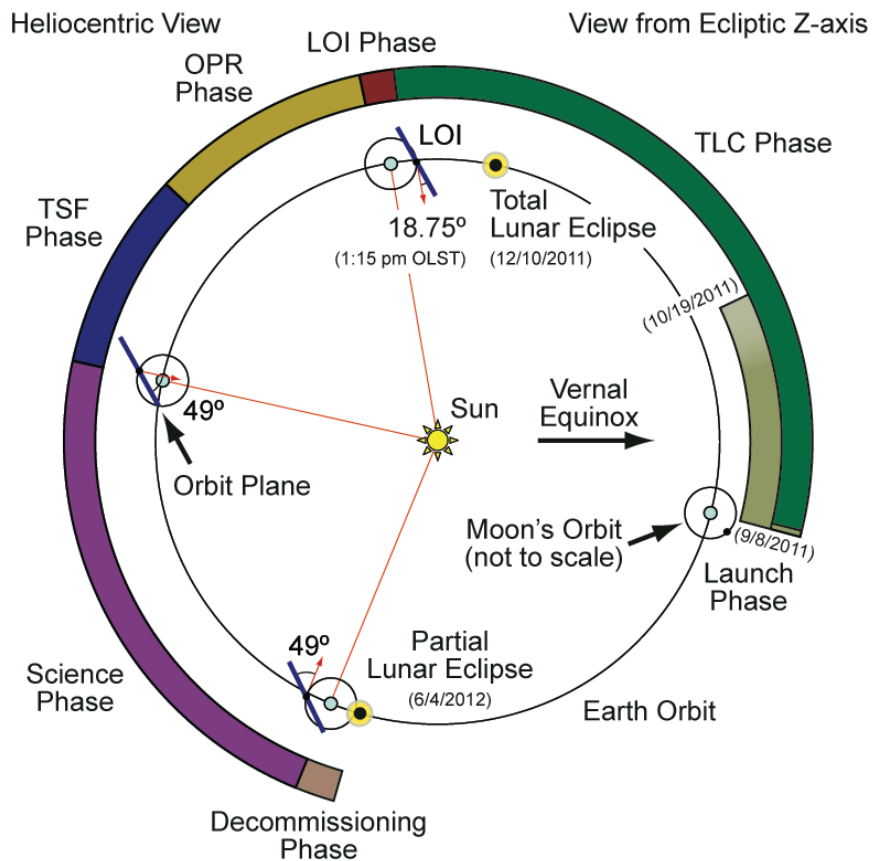




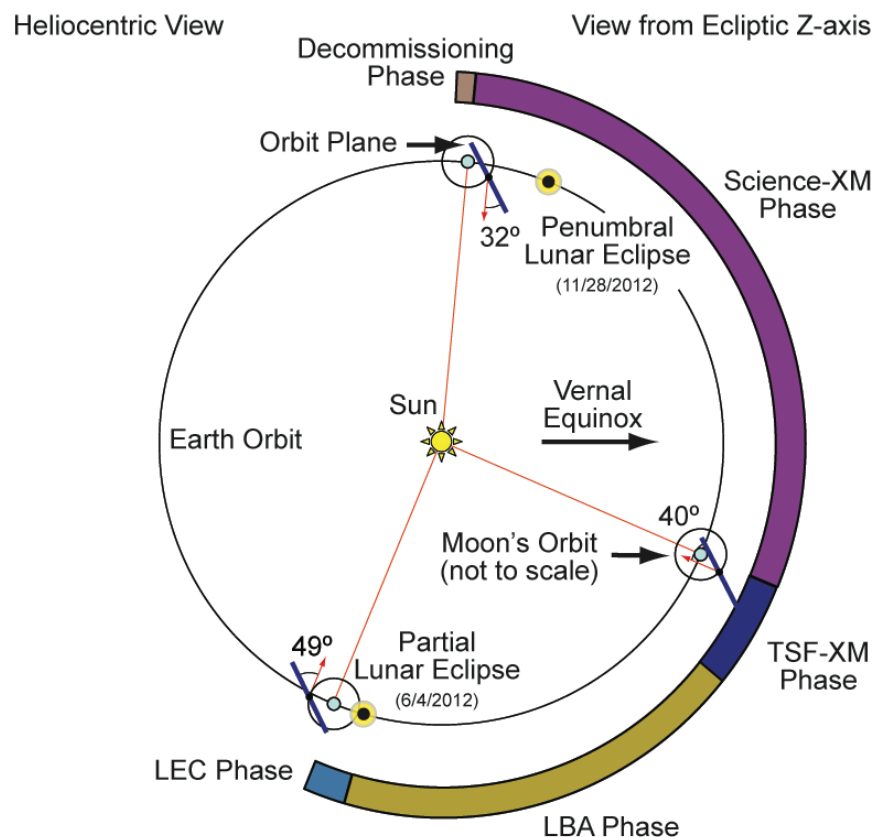
Mission Timeline / Mission Phases

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Primary GRAIL Mission

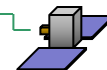
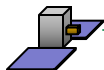


GRAIL Extended Mission

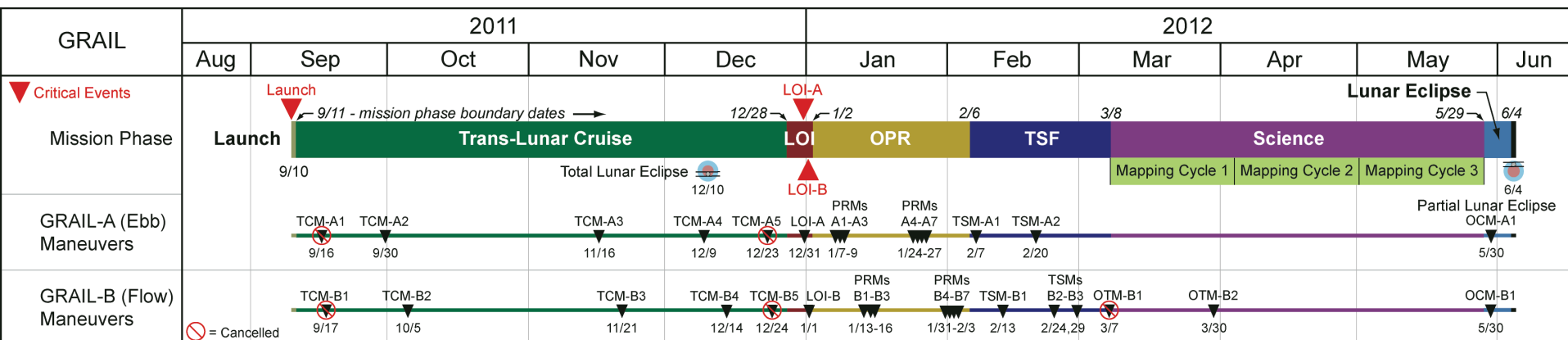




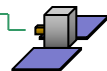
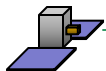
Primary Mission Maneuver Summary



- Number of Maneuvers Performed: 28
 - GRAIL-A (Ebb): 13 (2 cancelled)
 - GRAIL-B (Flow): 15 (3 cancelled)



- Maneuver Terminology**
 - TLC Phase: TCMs (Trajectory Correction Maneuvers)
 - LOI Phase: LOI (Lunar Orbit Insertion)
 - OPR Phase: PRMs (Period Reduction Maneuvers)
 - TSF Phase: TSMs (Transition to Science formation phase Maneuvers)
 - Science Phase: OTMs (Orbit Trim Maneuvers)



■ Launch

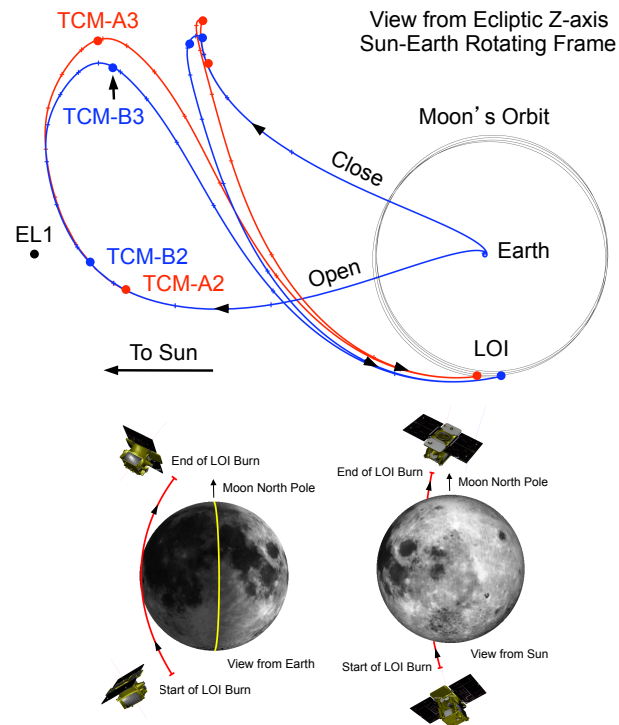
- Delta II 7920H-10C launch vehicle
- Launch period: 08-Sep-2011 through 19-Oct-2011
 - Total of 42 launch days (original LP was 26 days long)
- Constant arrival date (for all launch dates)
 - GRail-A: 31-Dec-2011
 - GRail-B: 01-Jan-2012 (Happy New Year!)

■ Trans-Lunar Cruise

- Low energy trajectory (3-4 month flight time to the Moon – 2 deterministic TCMs)
- First NASA mission to baseline this type of lunar transfer trajectory (but not the first to consider it)

■ Lunar Orbit Insertion

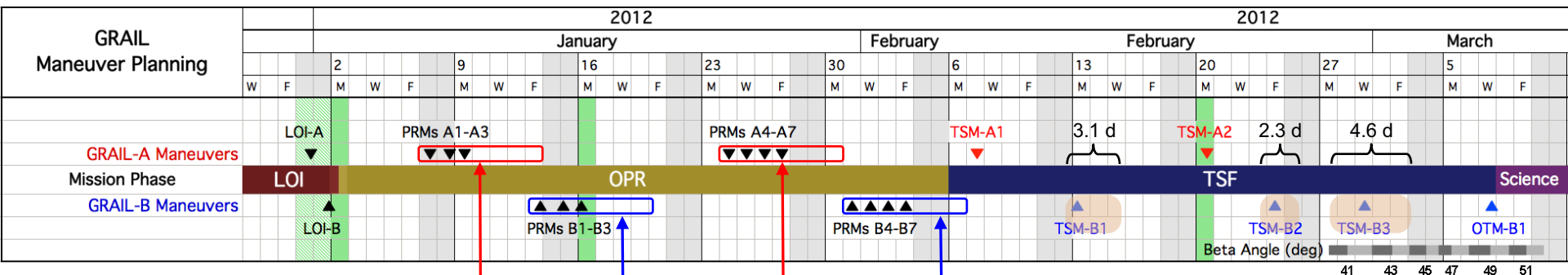
- LOI maneuvers separated by ~ 25 hours
- LOI maneuvers simultaneously visible from two Deep Space Network (DSN) tracking complexes
- LOI burn duration ~ 38 min ($\Delta V \sim 192$ m/s) resulting in a capture orbit period of 11.5 hours



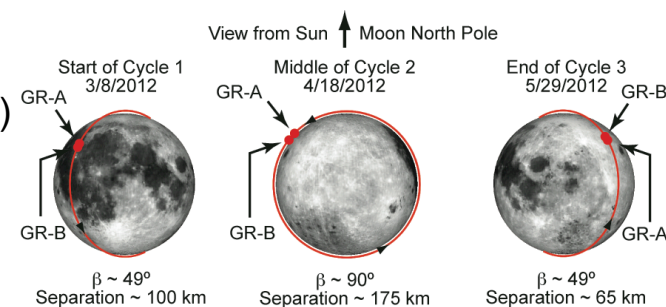
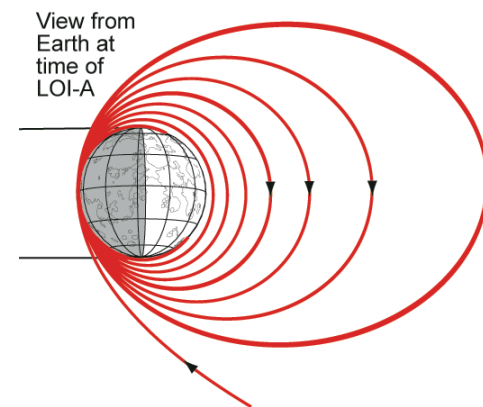


Primary Mission Overview – In Lunar Orbit

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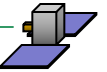
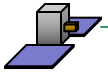


- **Orbit Period Reduction**
 - Single maneuver design repeatedly performed to reduce period
 - Orbit period reduced to just under 2 hours in one month
- **Transition to Science Formation**
 - Five maneuvers used to establish the proper formation for the collection of gravity science data
 - First time that two spacecraft have been independently maneuvered into a precise orbit formation about another solar system body (other than the Earth)
- **Science**
 - Planned 82 day Science Phase (ended up being 89 days long)
 - Near-polar, near-circular science orbit with a mean altitude of 55 km
 - No orbit maintenance maneuvers required, only maneuvers to change separation distance
 - Orbiter separation distance varied between ~ 82 km and 217 km

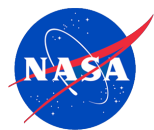




Advantages of a Low-Energy Lunar Transfer



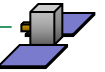
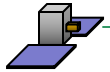
- General Benefits of a Low-Energy Transfer to the Moon
 - Reduction in spacecraft ΔV requirements as compared to the more common 3-6 day direct transfer trajectory (savings on the order of 120 m/s)
 - For GRAIL, this resulted in a lower cost mission option, allowing the use of a heritage spacecraft design and a smaller launch vehicle
 - Extended duration launch periods
 - Allows for launch period durations of more than 20 days
 - Fixed arrival date for all launch dates
 - Allows for the decoupling of trans-lunar cruise analyses from lunar orbit analyses
- GRAIL–Specific Benefits Using a Low-Energy Transfer to the Moon
 - Allowed time in cruise for spacecraft outgassing and stabilization of the Ultra Stable Oscillator (USO) prior to lunar orbit operations
 - Allowed time in cruise for system check-out and the ability to separate GRAIL-A and GRAIL-B TCMs
 - Allowed the ability to separate the GRAIL-A and GRAIL-B mission critical Lunar Orbit Insertion (LOI) maneuvers by one day



Low-Energy Trajectory Views

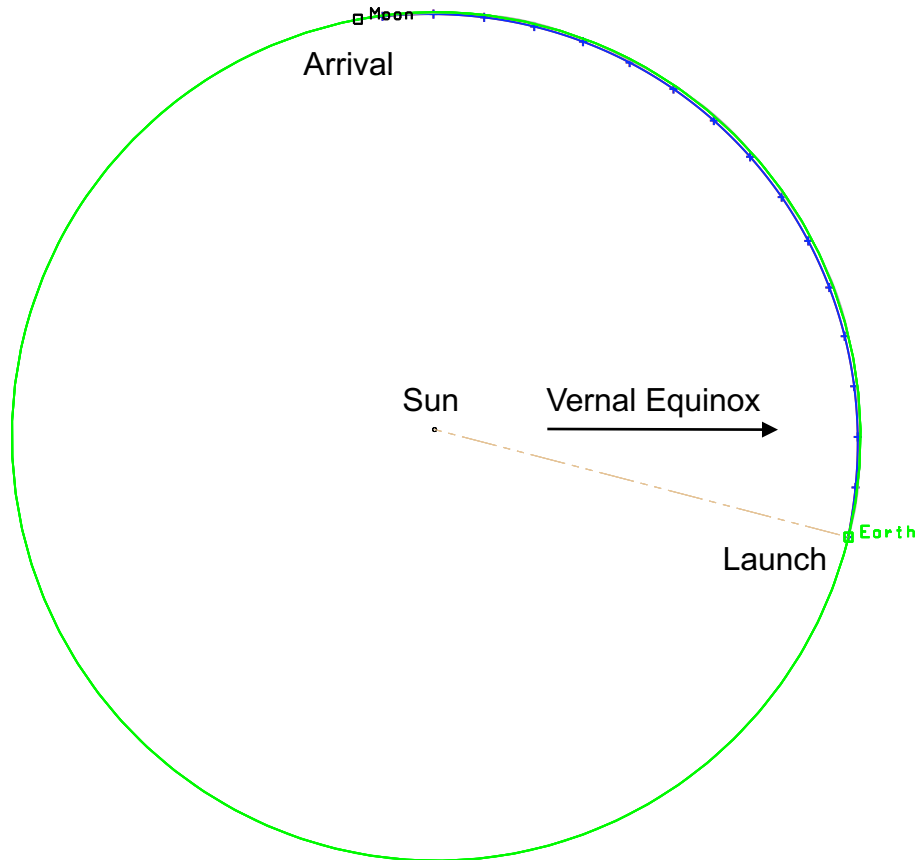
(Launch Period Open)

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Earth-Centered - Inertial View

Heliocentric View



Earth-Centered - Sun-Earth Rotating View

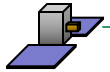




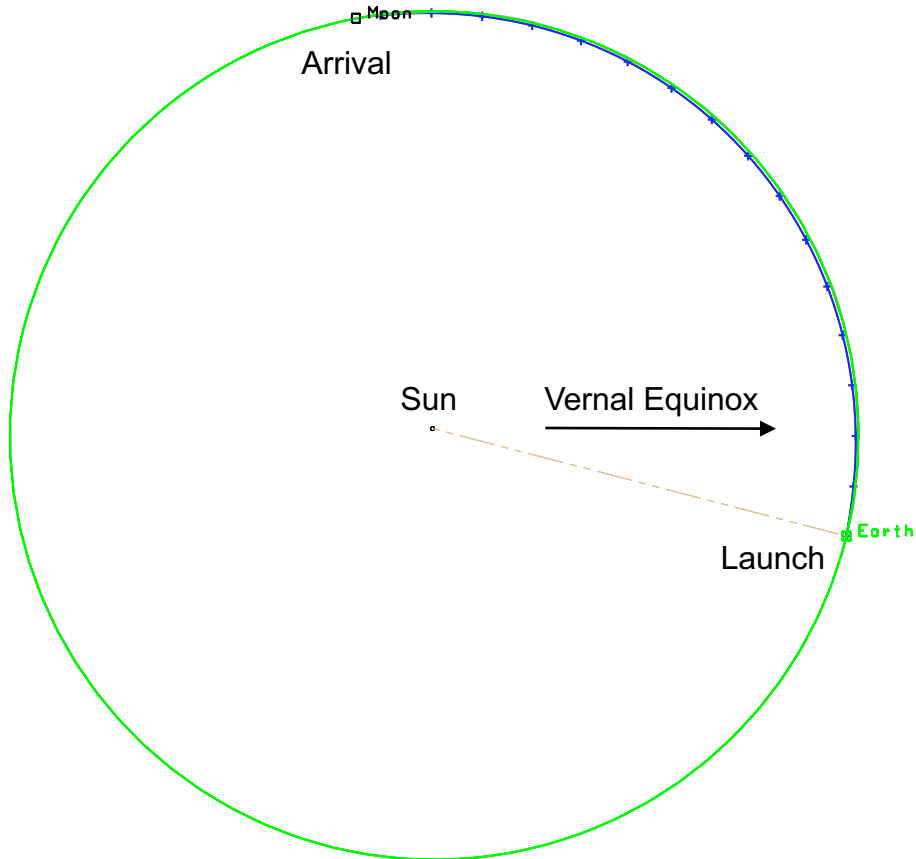
Low-Energy Trajectory Views

(Launch Period Open)

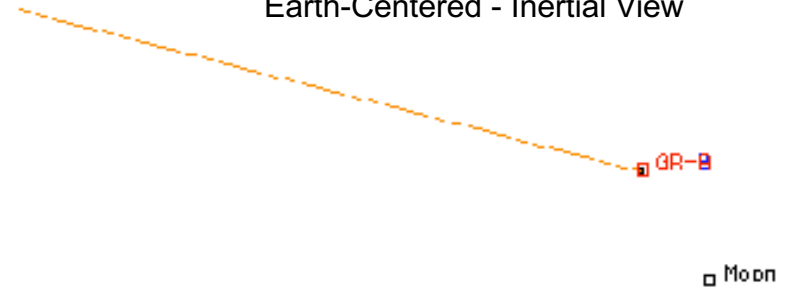
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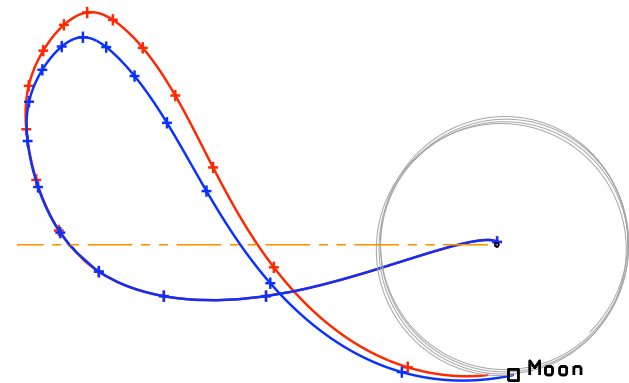
Heliocentric View

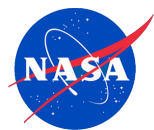


Earth-Centered - Inertial View



Earth-Centered - Sun-Earth Rotating View

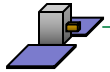




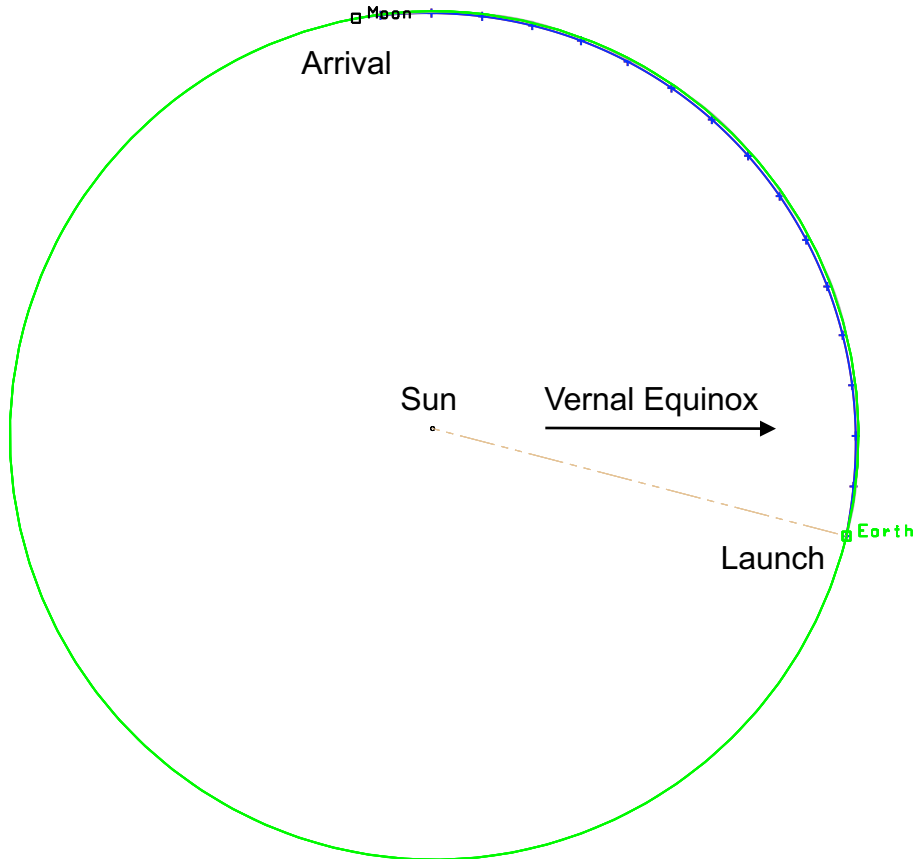
Low-Energy Trajectory Views

(Launch Period Open)

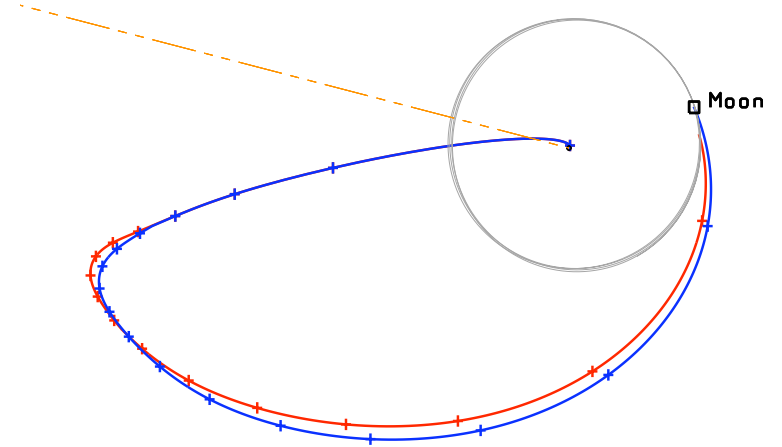
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Discovery



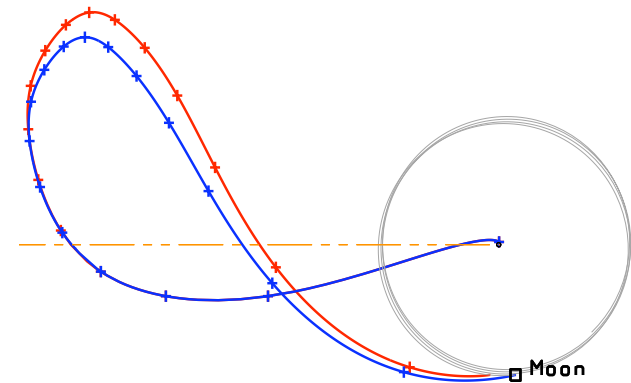
Heliocentric View



Earth-Centered - Inertial View

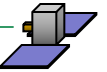
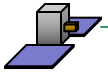


Earth-Centered - Sun-Earth Rotating View

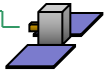
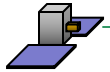




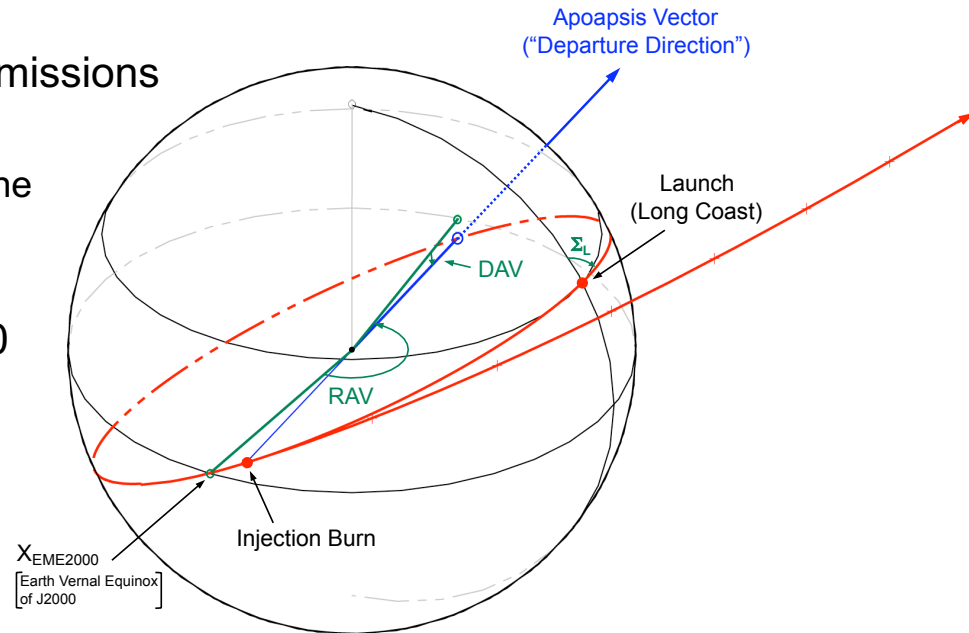
Trans-Lunar Cruise Trajectory Design



- General Characteristics of the TLC Trajectory
 - Launch trajectory along a stable manifold to a Lissajous orbit about the Sun-Earth Lagrange Point 1 (EL1)
 - However, instead of inserting into a Lissajous orbit – exit via an unstable manifold to the Moon
- Dual Spacecraft Launch on a Single Launch Vehicle
 - Two deterministic TCMs
 - TCM-2: Arrival time (LOI) separation
 - TCM-3: Manifold insertion
 - Three statistical TCMs
 - TCM-1: Correct launch vehicle injection errors
 - TCMs 4 and 5: Correct orbit determination errors and maneuver execution errors

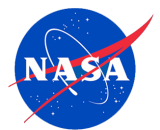


- LOI Targets at the Moon
 - Arrival time, capture orbit period, periapsis altitude, orbit inclination, orbit node, approach direction (over the lunar south pole), latitude of periapsis – ALL FIXED
 - Only free variable is the instantaneous LOI ΔV magnitude (constrained to be in-plane)
- Injection (Launch) Targets at Earth
 - Traditional targets for interplanetary missions
 - Departure energy (C_3) (positive)
 - Declination and Right Ascension of the departure asymptote (DLA and RLA)
 - Low-energy trajectory does not have a “departure asymptote” since $C_3 < 0$
 - Analogous set of targets for GRAIL
 - Departure energy (C_3) (negative)
 - Declination and Right Ascension of the apoapsis vector (used to represent the “departure direction”) (DAV and RAV)
 - First time that this approach has been used by any mission
 - Position and injection time determined by launch site and parking orbit

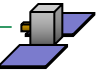
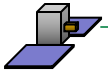


GRAIL Launch Targets

C_3 (twice the injection energy per unit mass, km^2/s^2)
 DAV (declination of the injection orbit apoapsis vector, deg, EME2000)
 RAV (right ascension of the injection orbit apoapsis vector, deg, EME2000)



Trajectory Optimization

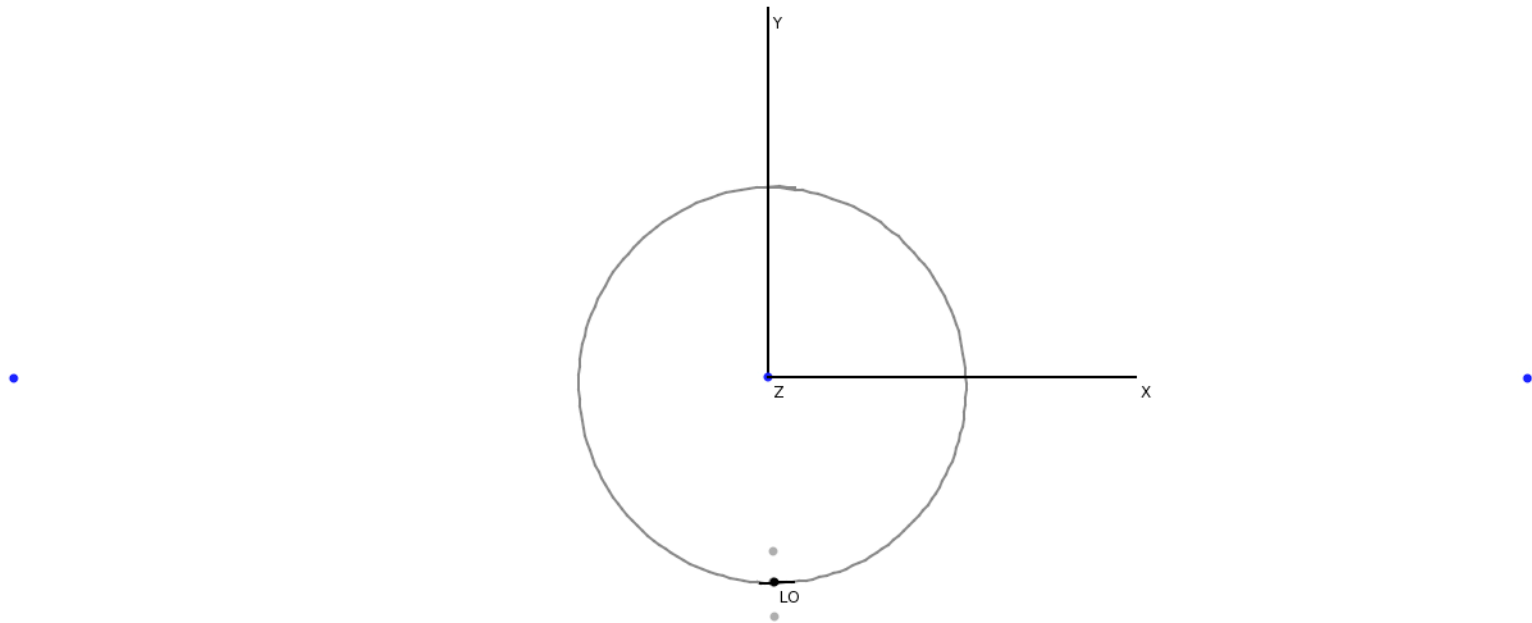
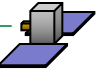
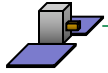


- Theoretical Solution
 - Differentially correct two segments
 - A stable manifold to an EL1 Lissajous orbit from launch, and
 - An unstable manifold from the EL1 Lissajous orbit to the Moon
- Practical Solution
 - Search on the LOI ΔV magnitude until the backward propagated trajectory reaches the Earth approximately at the launch time
 - The backward propagated trajectory is a good estimate of the differentially-corrected segments except that the launch conditions are not met
 - Search on a launch trajectory that inserts into the backward propagated manifold and minimizes the total TLC ΔV (with TCMs at specified times)



Illustration of TLC Trajectory Design Process

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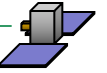
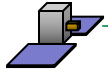




Visualization of TLC Trajectory

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[Depiction of the Change in Two-Body Ellipse about the Earth due to the Sun and the Moon]



SCET: 2011 Sep 10 13:38:09 (UTC)
Spacecraft Separation: 0 km
GRAIL-A Altitude: 399809 km
GRAIL-B Altitude: 399809 km
Range to Earth: 166 km
Lunar location: 5.40 E, 6.11 S
Nadir area dark: False

Sun on the Left

EL1

Earth

Moon

113 days to Planned LOI-A Burn Start

Time Multiplier: 272942



Click and drag to adjust the view



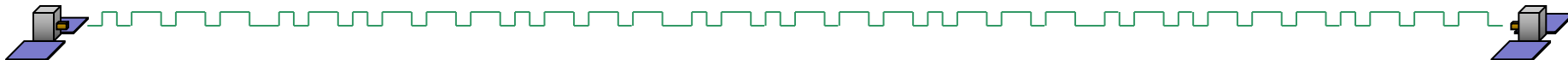
GRAIL-A
Maneuvers



GRAIL-B
Maneuvers

| | | | | | | | | | | | | | |
|--------|--------|--------|--------|--------|-------|---------|----------|-------|---------|--------|--------|--------|--|
| TCM-A1 | TCM-A2 | TCM-A3 | TCM-A4 | TCM-A5 | LOI-A | AT-A3 | PRM-A | PRM-A | PRM-A | TSM-A1 | TSM-A2 | | |
| 9/16 | 9/20 | 11/16 | 12/9 | 12/23 | 12/31 | 1/7/9 | 1/24/27 | 2/7 | 2/20 | | | | |
| TCM-B1 | TCM-B2 | TCM-B3 | TCM-B4 | TCM-B5 | LOI-B | BI-B3 | PRM-B | PRM-B | PRM-B | TSM-B1 | OTM-B1 | OTM-B2 | |
| 9/17 | 10/5 | 11/21 | 12/14 | 12/24 | 1/1 | 1/13-16 | 1/31-2/3 | 2/13 | 2/24-29 | 3/7 | 3/20 | | |



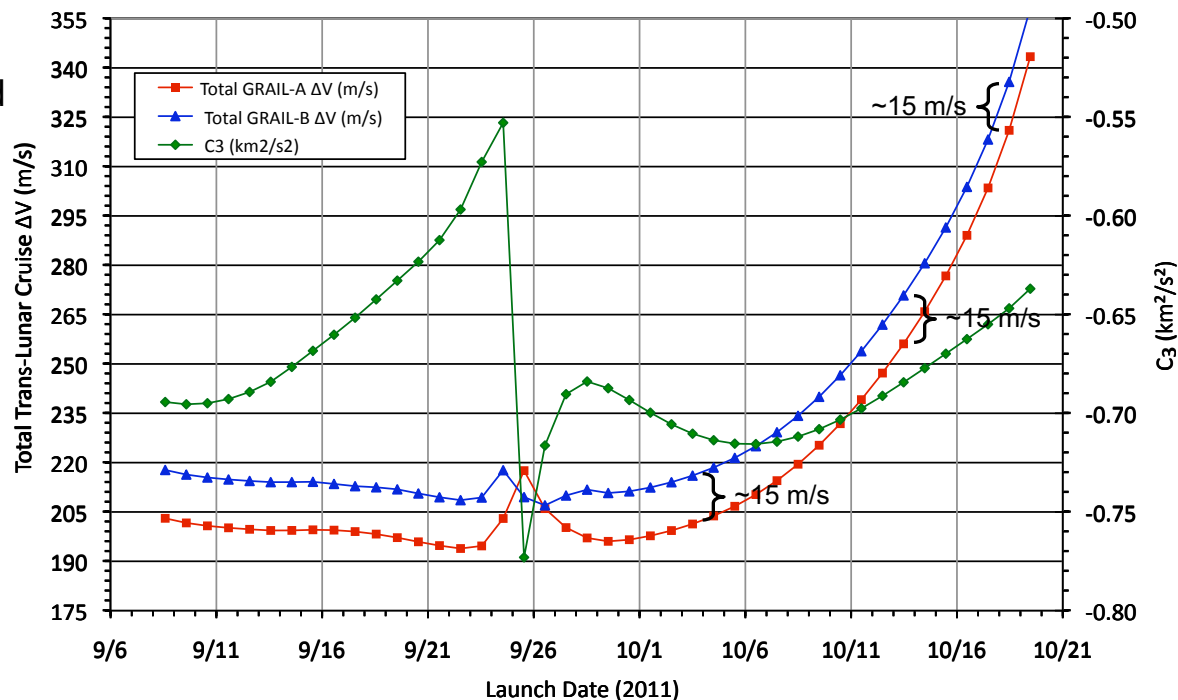


■ Baseline Launch Period

- Minimize ΔV across launch period
- Originally launch period was 26 days

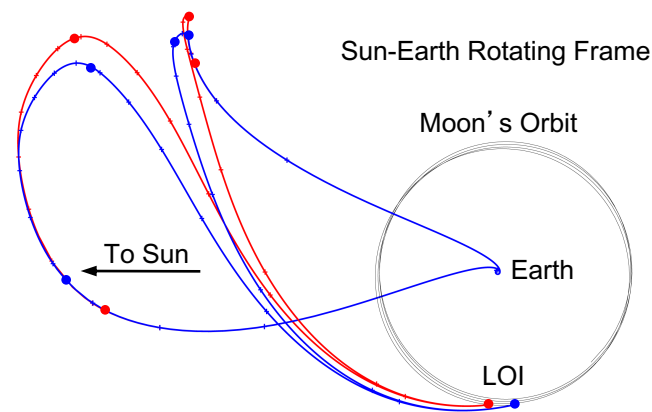
■ Balance GR-A and GR-B ΔV s

- Weight the GR-A and GR-B ΔV s such that the difference in ΔV s is the same from day to day
 - Attempt to ensure that the end-of-mission ΔV margin is the same for GR-A and GR-B



■ Extended Launch Period

- Constrained by
 - Available propellant
 - Compression of Trans-Lunar Cruise timeline (ability to “fit” all activities into a shortened TLC Phase)
- Final launch period was 42 days long !

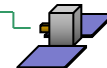
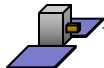




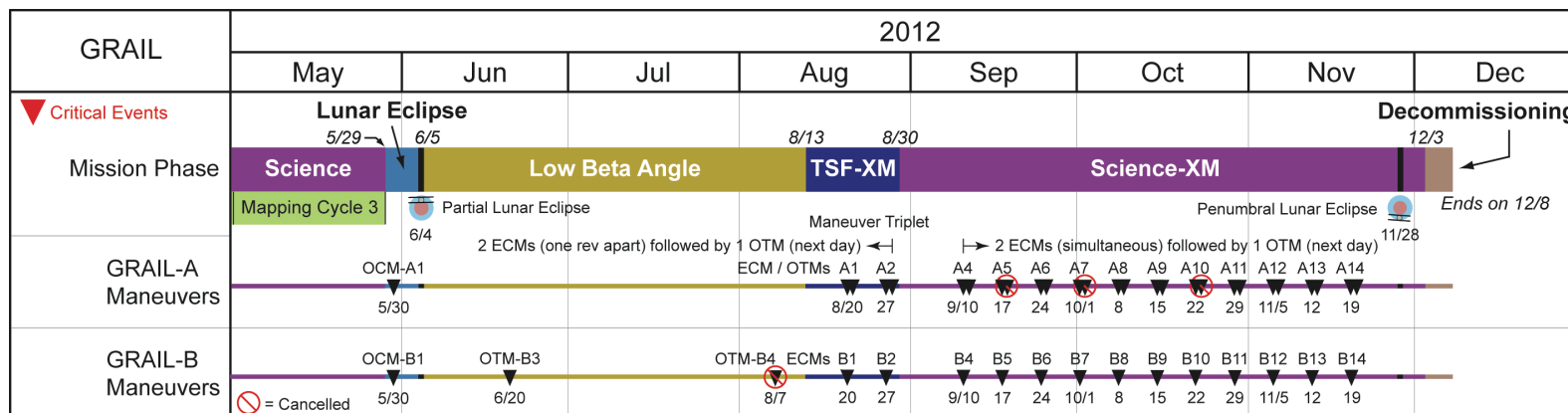
Extended Mission Maneuver Summary

(Excluding End Game)

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- Number of Maneuvers Performed: 39
 - GRAIL-A (Ebb): 24 (3 cancelled)
 - GRAIL-B (Flow): 15 (1 cancelled)



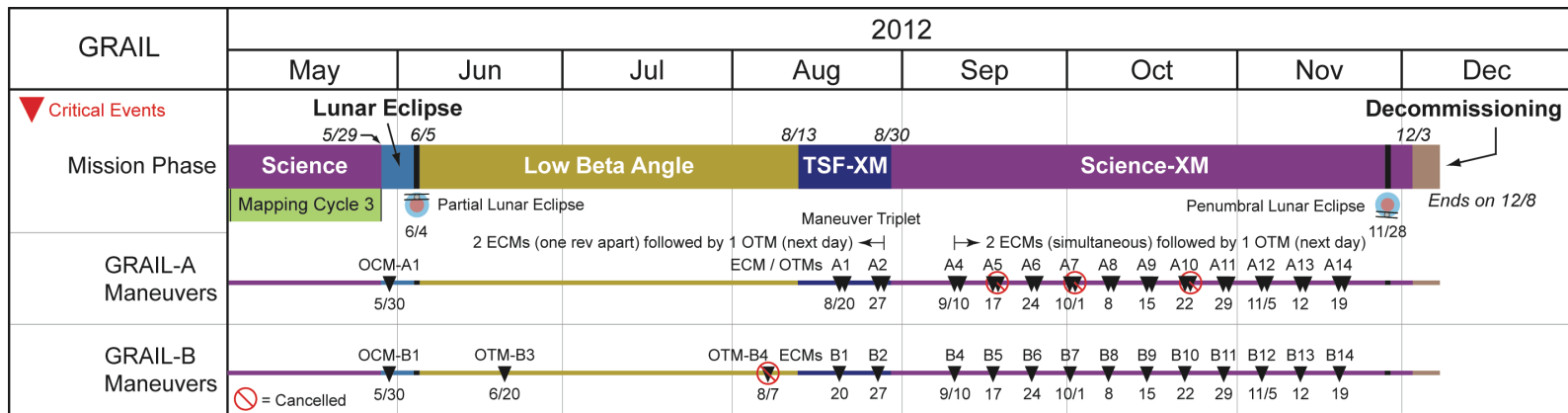
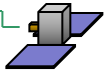
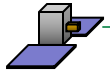
Maneuver Terminology

- LEC Phase: OCMs (Orbit Circularization Maneuvers)
- Multiple Phases: ECMs (Eccentricity Correction Maneuvers)
- Multiple Phases: OTMs (Orbit Trim Maneuvers)

Before End Game
was developed



Extended Mission Overview



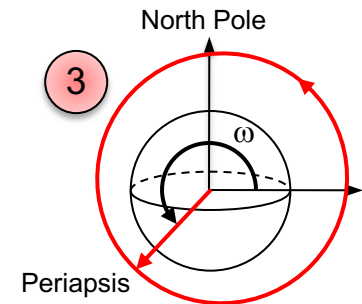
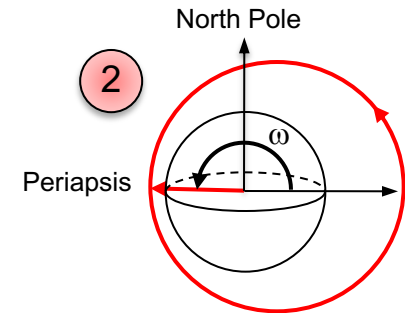
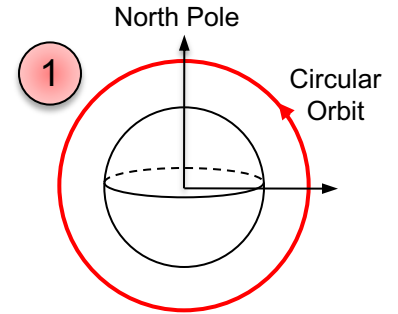
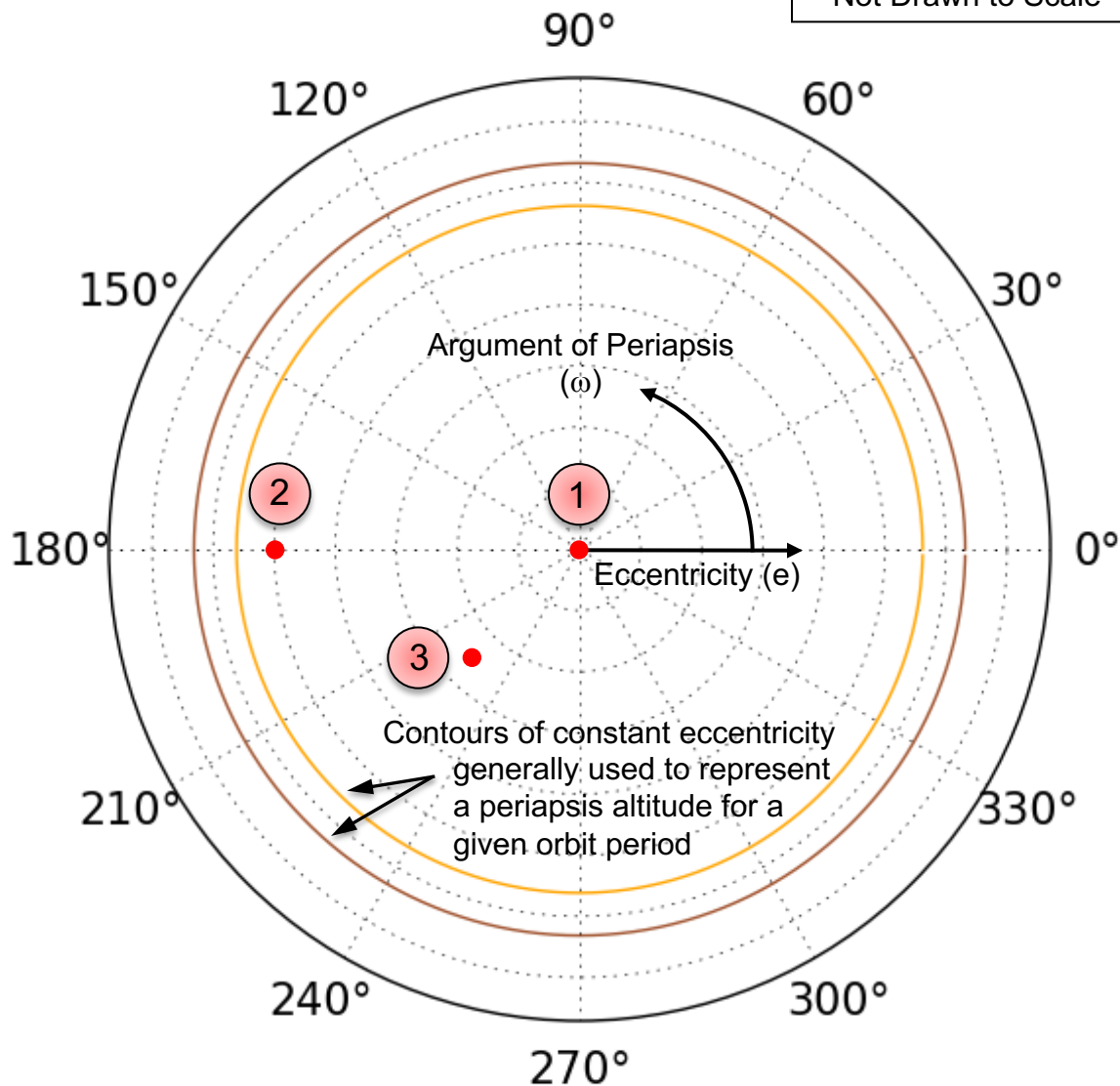
- **Lunar Eclipse**
 - Avoid impacting the surface and prepare for passage through the partial lunar eclipse
- **Low Beta Angle**
 - No science possible – manage the separation rate between the two orbiters to achieve the desired separation distance in mid August
- **Transition to Science Formation – Extended Mission**
 - Lower the orbit altitude to the new science orbit and establish the initial conditions for the next phase
- **Science – Extended Mission**
 - Perform “standard triplet of maneuvers” every week for 14 weeks (except Labor Day!) in order to
 1. Manage the evolution of the eccentricity and argument of periapsis (i.e. the eccentricity vector)
 2. Control the separation distance by adjusting the separation rate prior to the next set of maneuvers
 - Achieve a mean orbit altitude of 23.5 km with a targeted separation distance of 60 km
- **Decommissioning**
 - “Disposing” of the spacecraft in a scientifically interesting way was TBD for much of the XM

Before
End Game
was developed

Introduction to Eccentricity Vector Space

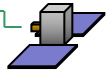
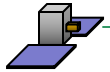


Not Drawn to Scale

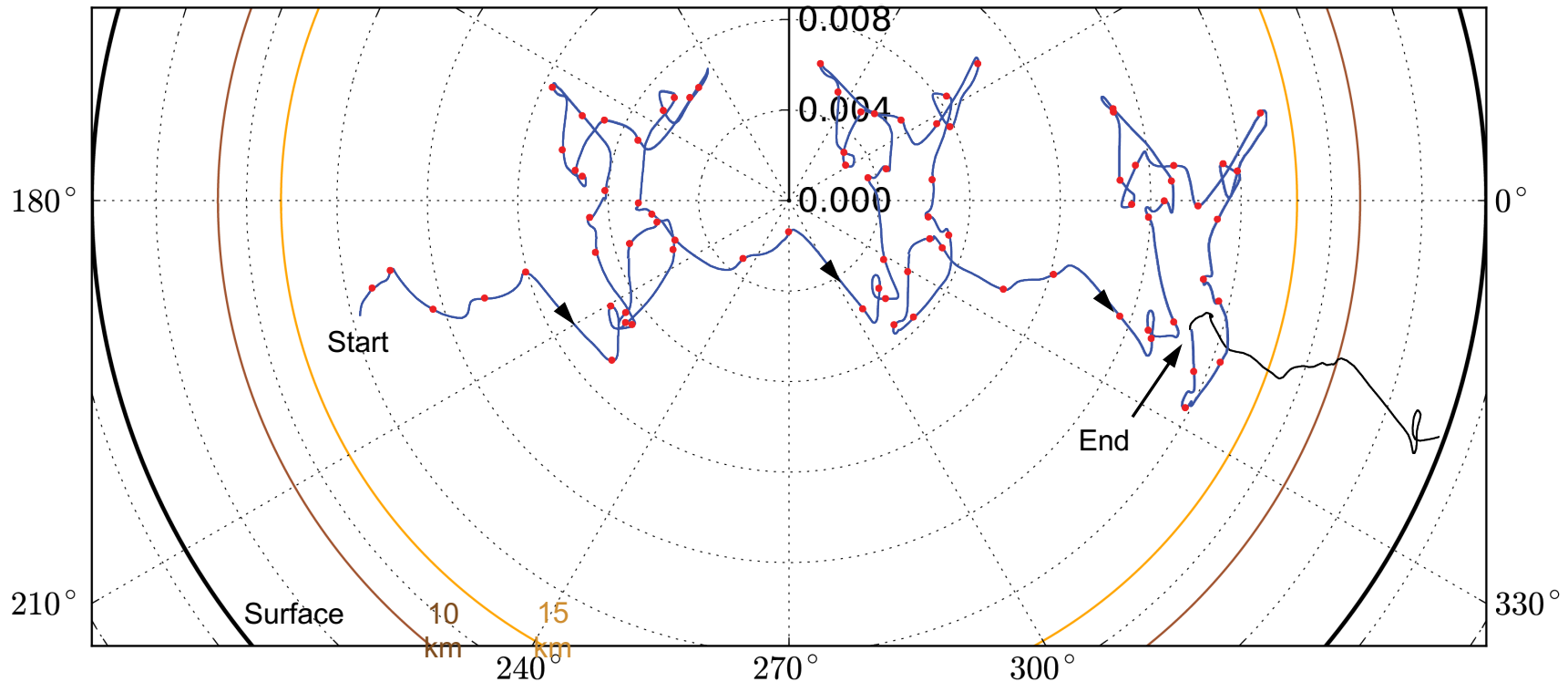




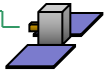
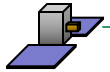
e- ω Plot for Primary Mission Science Phase



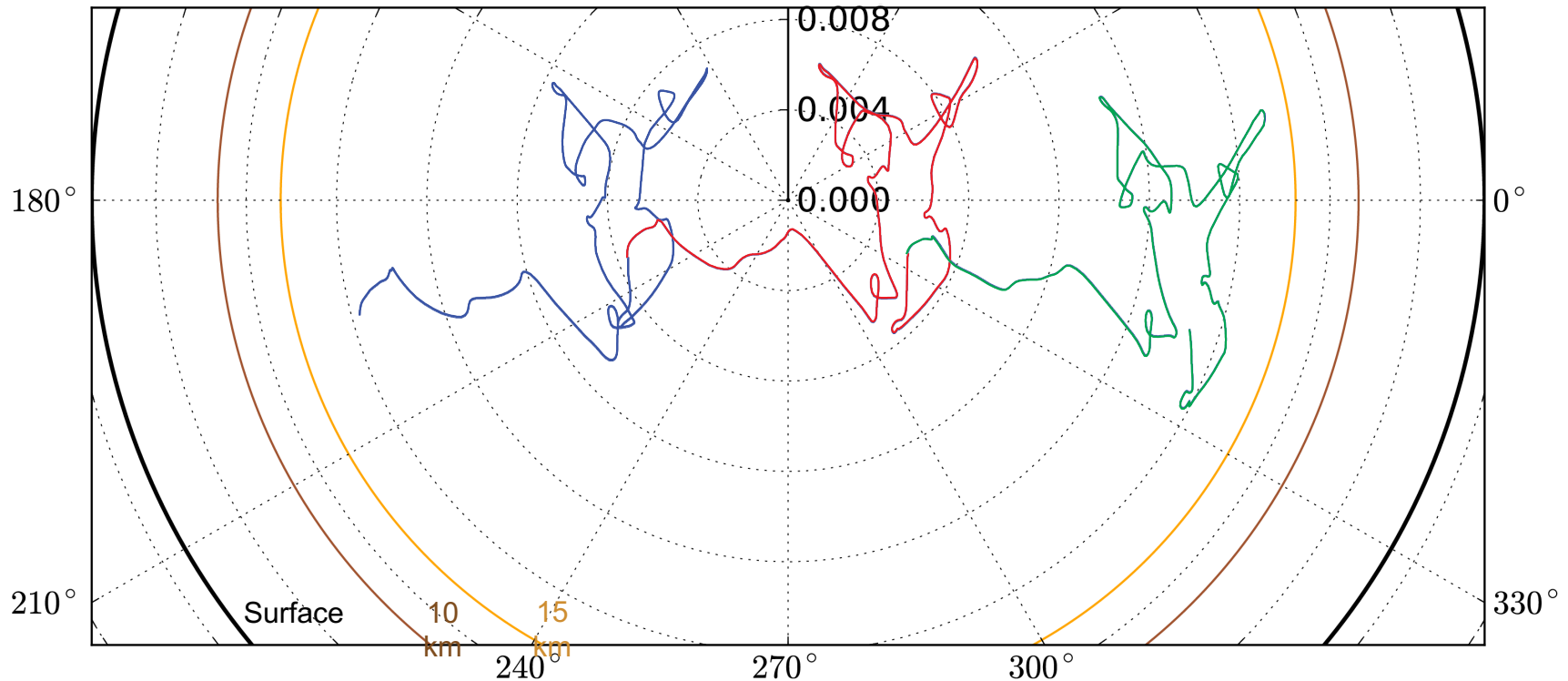
- Primary Mission Science Phase = 82 days
 - March 8th to May 29th, 2012
 - 3 lunar sidereal months (3 x 27.3 days) = 3 Mapping Cycles
- Mean orbit altitude = 55 km
 - No orbit maintenance maneuvers – orbit evolves from elliptical, to near-circular, back to elliptical



Managing the e- ω Evolution



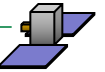
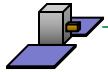
- Adding Maneuvers
 - To minimize the maximum altitude variation and potentially lower the mean orbit altitude
- Consider the case of performing a maneuver after each Mapping Cycle (27.3 days)
- Centering the e- ω evolution minimizes the maximum altitude variation



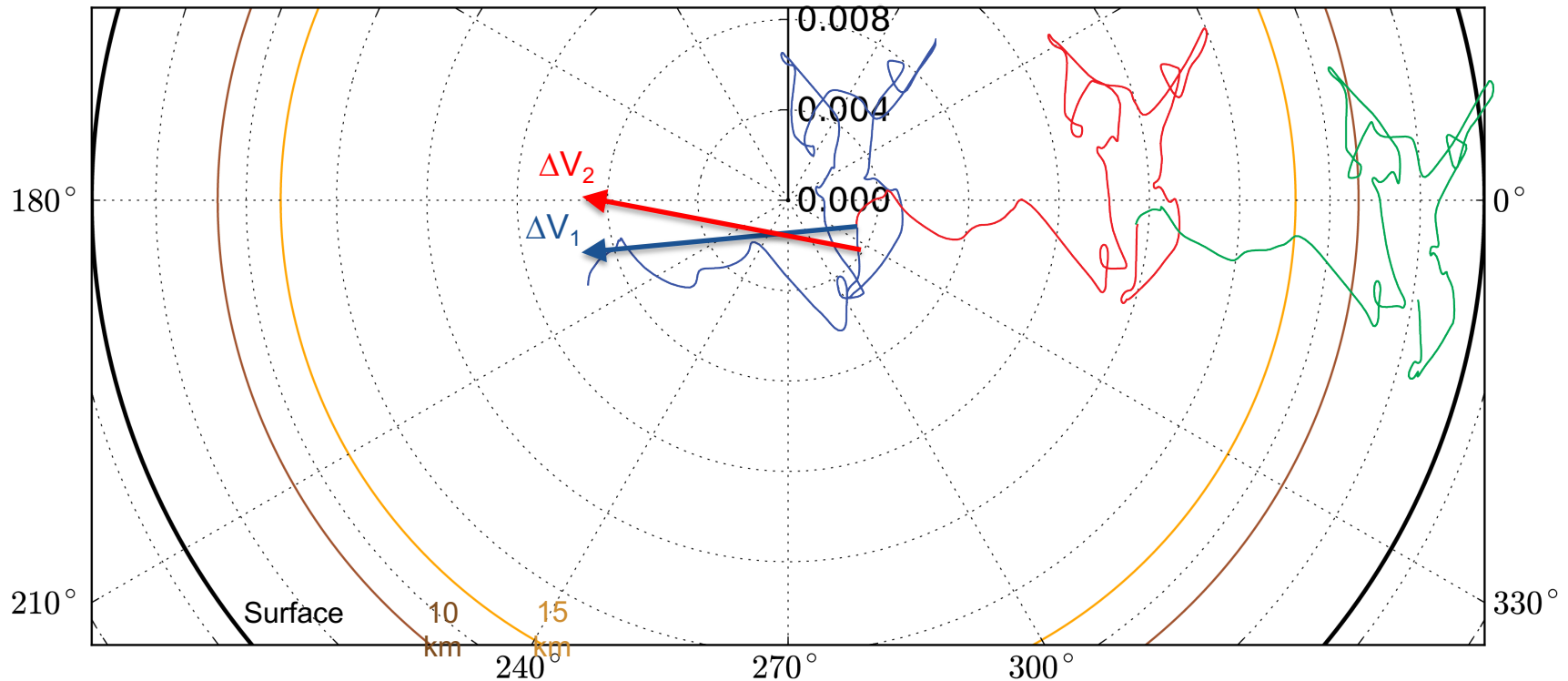
Lunar gravity field = LP150Q (150x150)



Managing the e- ω Evolution

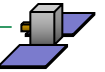
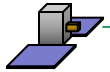


- Adding Maneuvers
 - To minimize the maximum altitude variation and potentially lower the mean orbit altitude
- Consider the case of performing a maneuver after each Mapping Cycle (27.3 days)
- Centering the e- ω evolution minimizes the maximum altitude variation

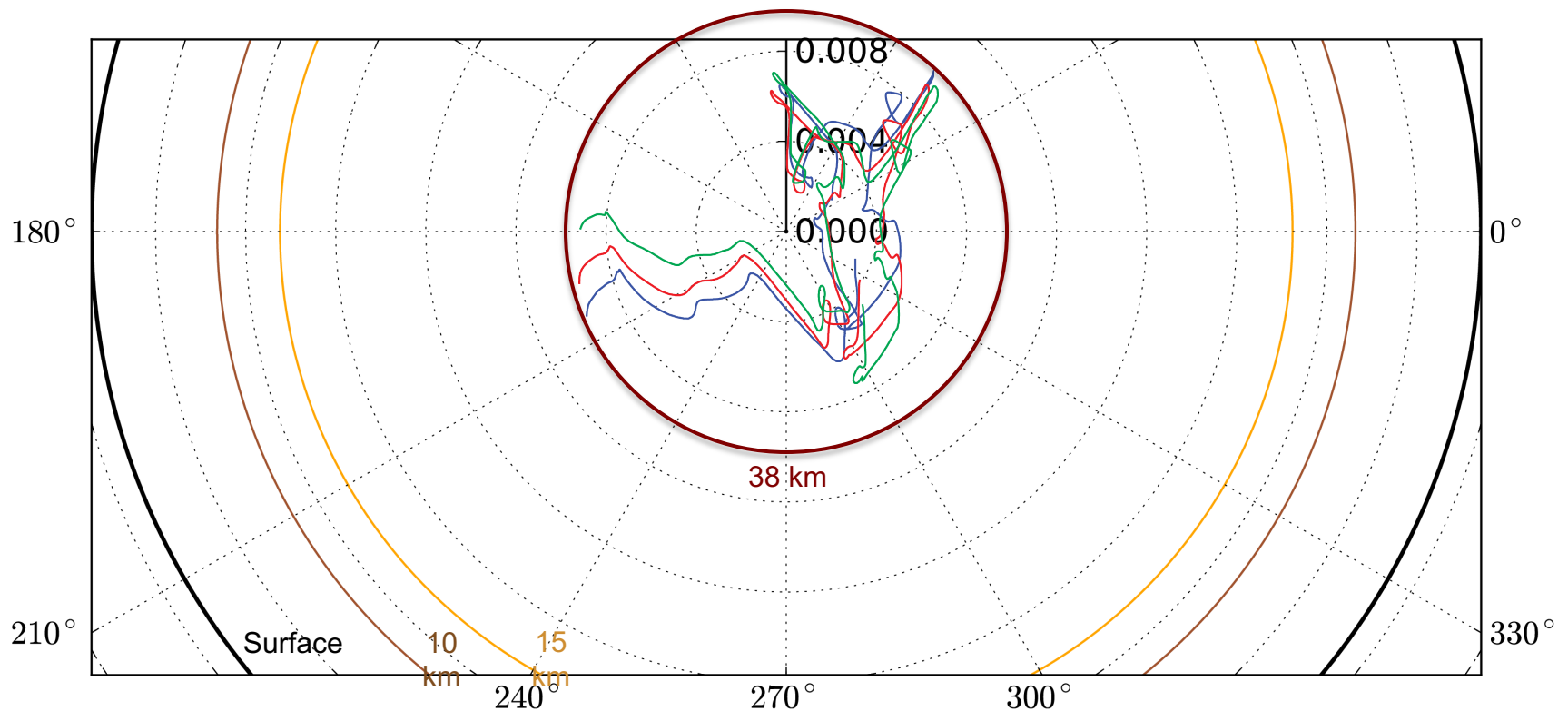


Lunar gravity field = LP150Q (150x150)

Managing the e- ω Evolution

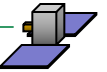
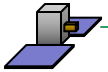


- Adding Maneuvers
 - To minimize the maximum altitude variation and potentially lower the mean orbit altitude
- Consider the case of performing a maneuver after each Mapping Cycle (27.3 days)
- Centering the e- ω evolution minimizes the maximum altitude variation





Extended Mission Science Orbit Design

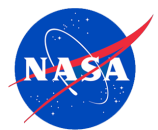


■ Principal Design Factors

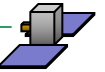
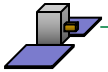
- Science
 - Mean orbit altitude – as low as possible
 - Maximum altitude variation (max apoapsis to min periapsis) – as small as possible
- Operations / Flight System
 - Frequency of “orbit reset maneuvers” (or ECMs – for Eccentricity Correction Maneuvers)
 - » Don’t change existing operations processes (e.g. maneuver development templates)
 - Orbit lifetime – ensure a minimum orbit lifetime of at least 7 days in the case of a missed maneuver
 - ΔV requirements – smaller is better, but little need to save ΔV for future use

■ Trade Space

- Evaluated many different options, but focused primarily on operationally simple options with maneuvers performed
 - Once every 28 days
 - Once every 14 days
 - Once every 7 days
 - Evaluated different “days-of-the-week” for maneuvers --- it matters !

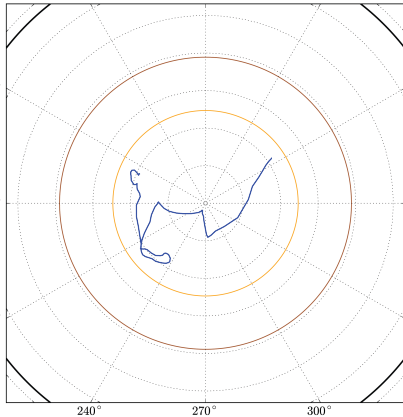


Making the 7-day Reset Option Work

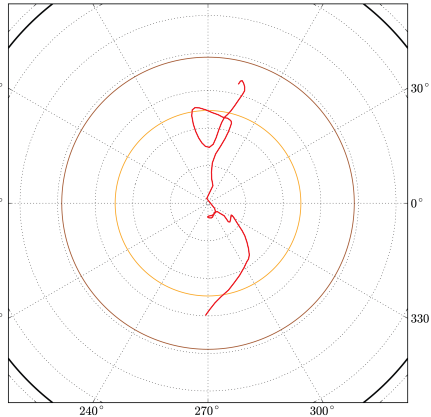


- Centering the weekly e- ω segments – 1st month

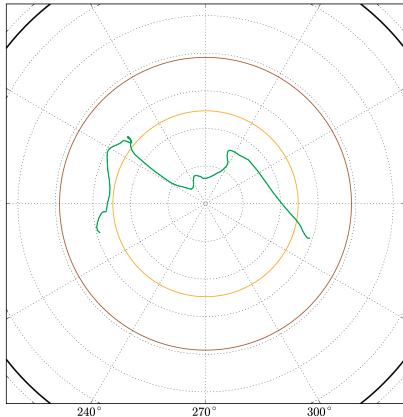
Week 1



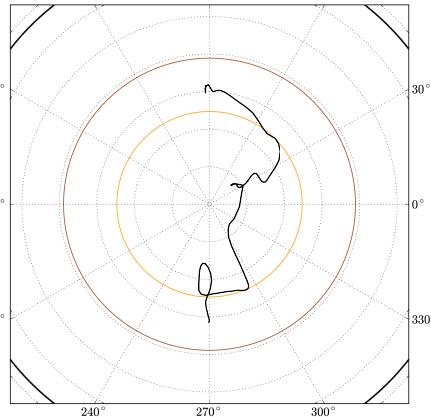
Week 2



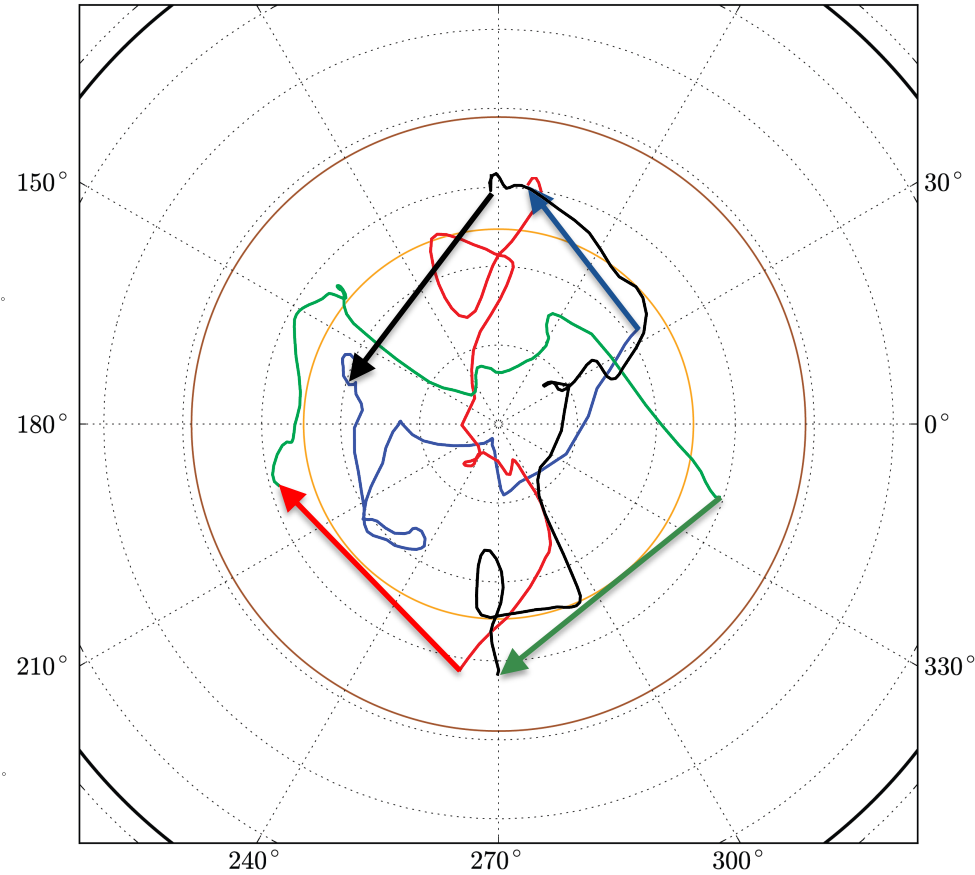
Week 3



Week 4



First 4 Weeks

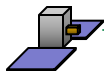


- and repeat for 2 more months ...
- and then repeat again varying the ECM day-of-the-week, optimizing ΔV , and so on ...

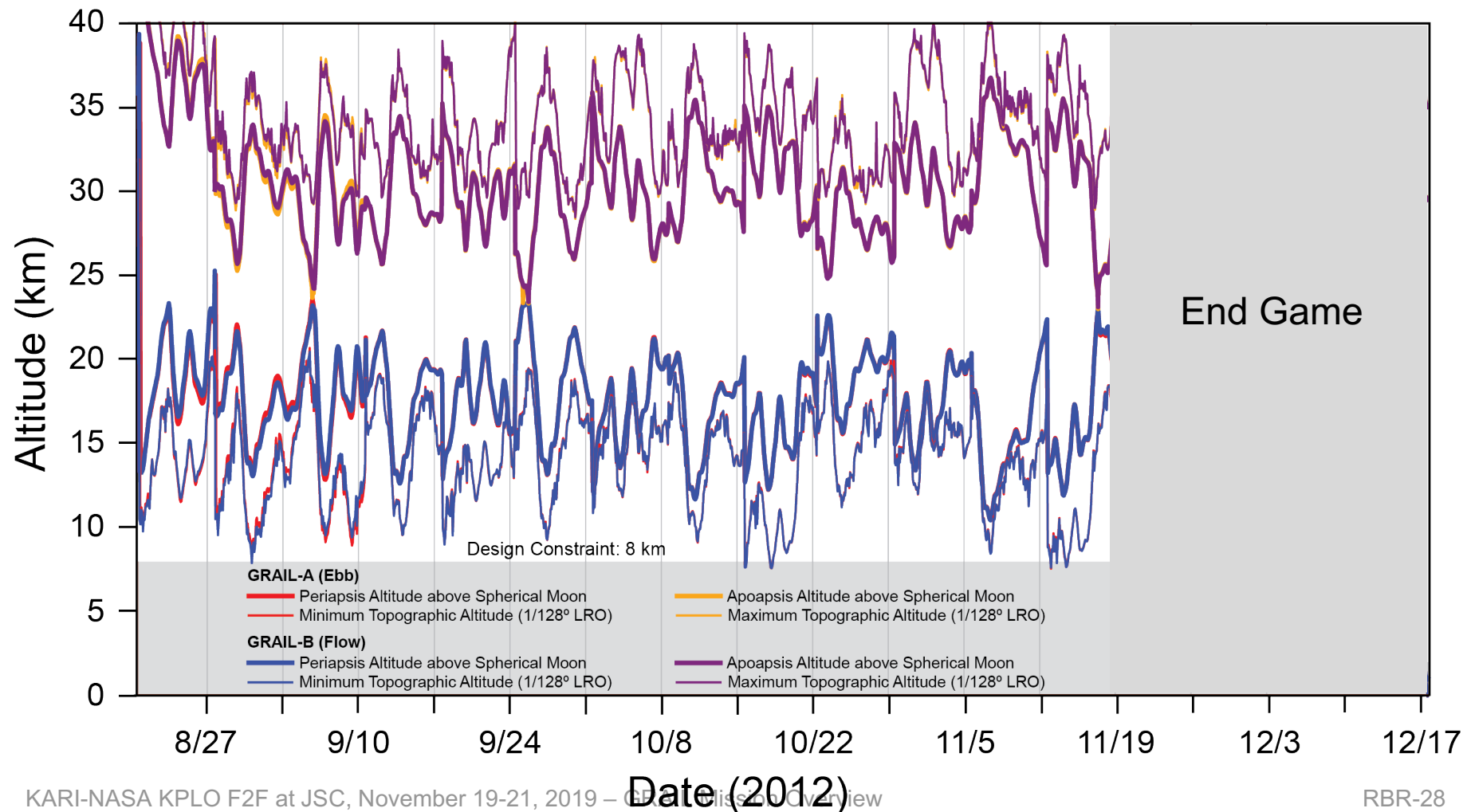
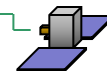


GRAIL Extended Mission Science Orbit

GRAIL
Discovery

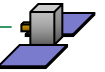
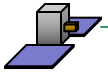


- GRAIL-PM: Mean orbit altitude = 55.0 km
- GRAIL-XM: Mean orbit altitude = 23.5 km





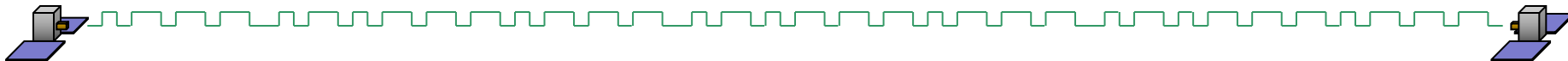
End Game Objectives



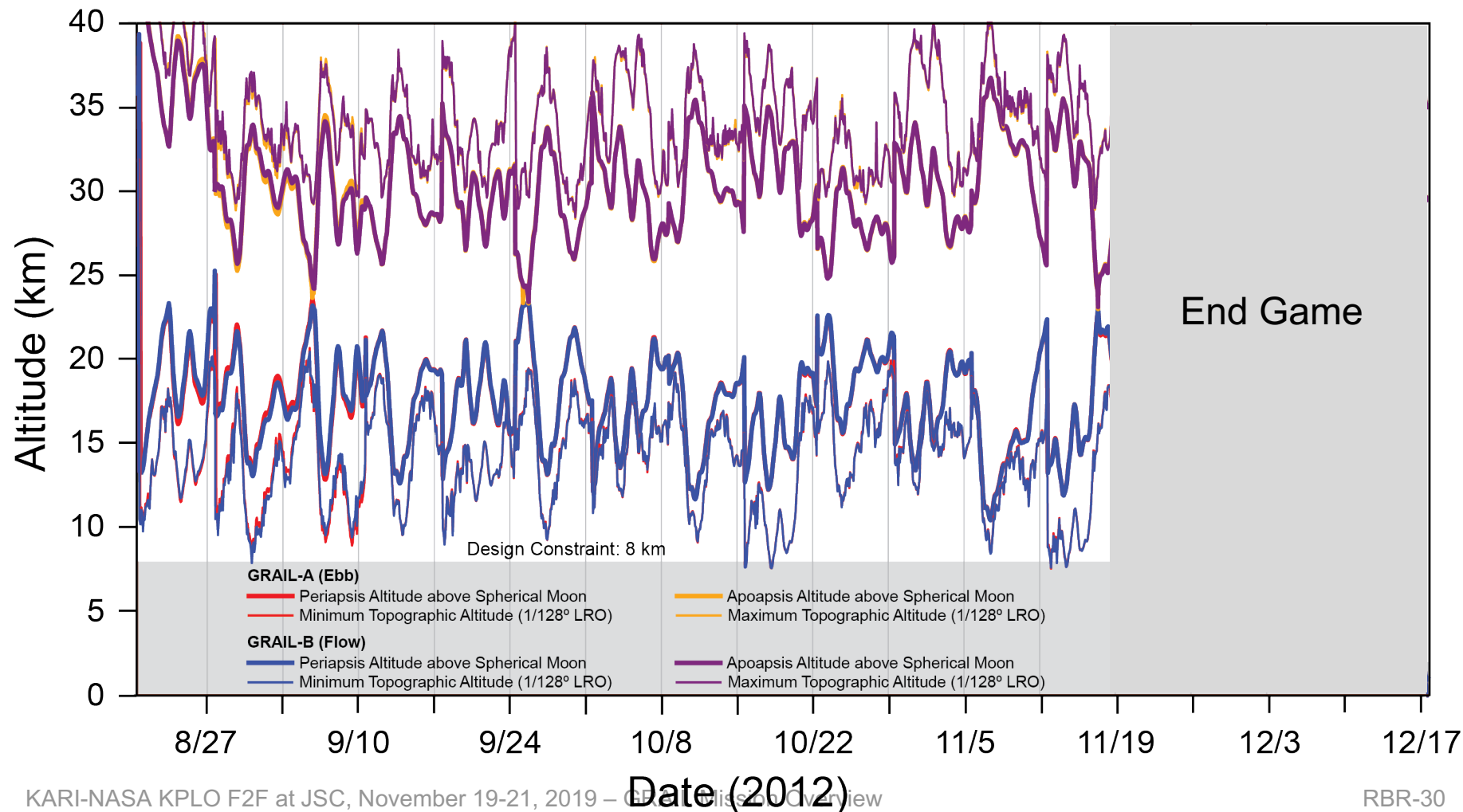
- Original End-of-Mission (as described in the proposal submitted to NASA in March 2012)
 - No specific End Game objectives were identified
 - Final maneuvers on were November 19th (no change in mean altitude from earlier maneuvers)
 - Orbit would evolve to an impact on or about December 7th
- What to do? How to get the most out of the mission?
 - Impact a crater wall? Collect more gravity science data?
- Conclusion (reached during the late summer / early fall of 2012)
 - Continue to collect gravity science data for as long as possible at lower and lower altitudes!
- Constraints on End Game Duration
 - Spacecraft
 - Power and Thermal – limits duration of science data collection
 - Available propellant – limits orbital lifetime
 - Site Impact Targeting
 - Minimize the potential of disturbing “Lunar Heritage Sites”

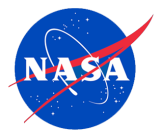


GRAIL Extended Mission Science Orbit



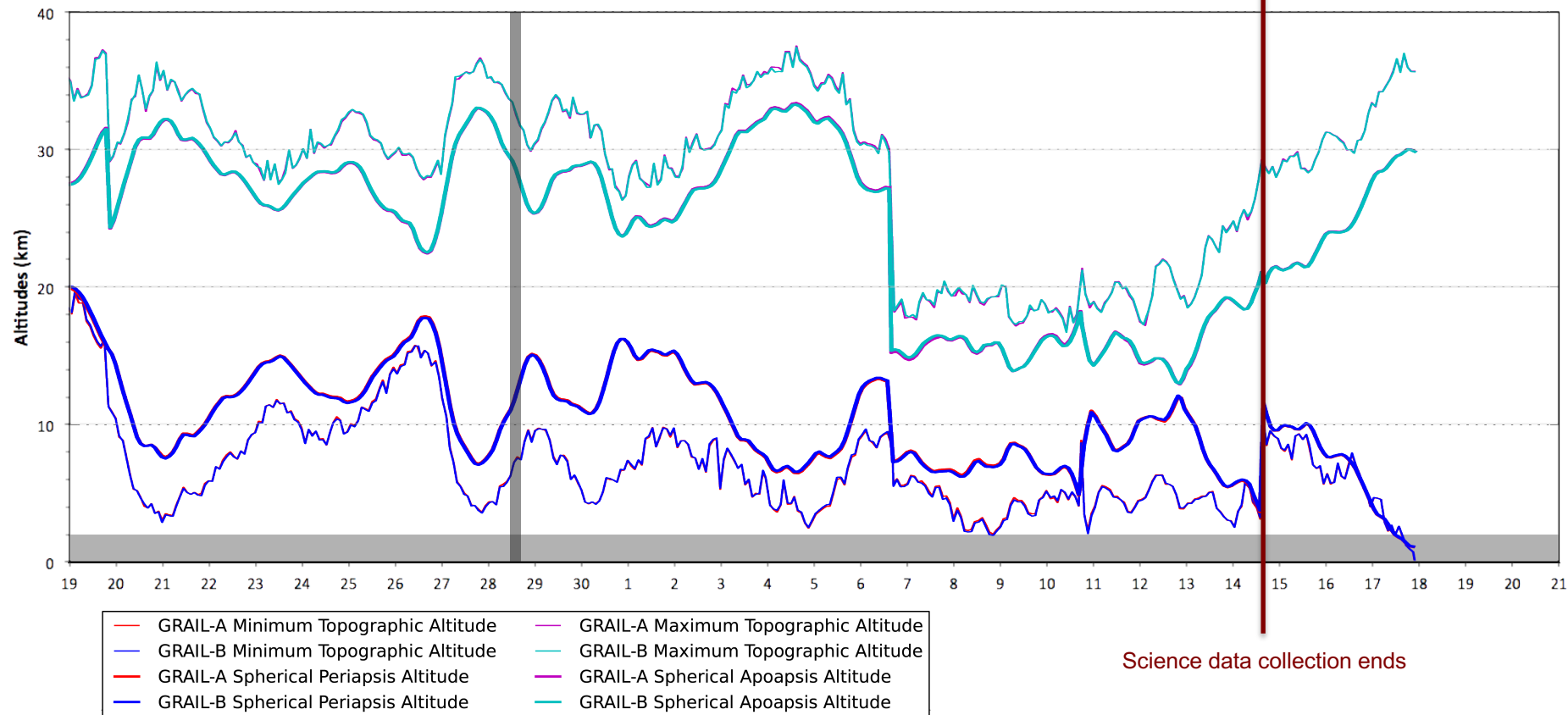
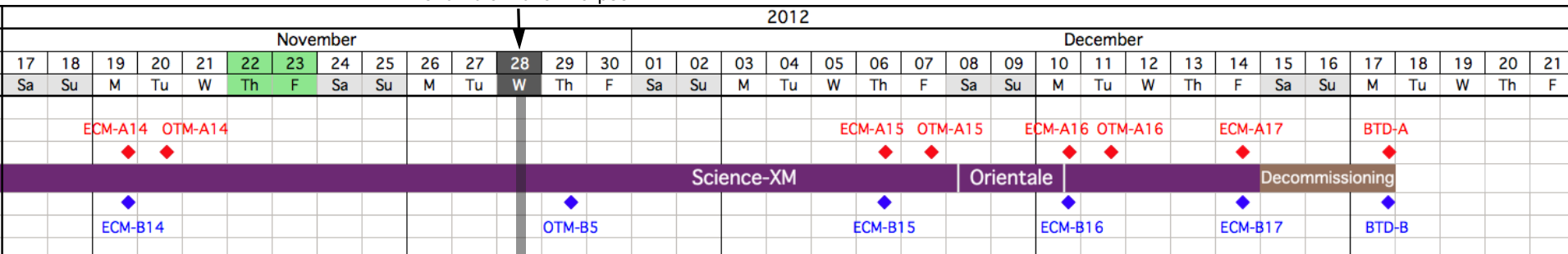
- GRAIL-PM: Mean orbit altitude = 55.0 km
- GRAIL-XM: Mean orbit altitude = 23.5 km
- End Game: Mean orbit altitude = 23.5 km to 20.0 km to 11.5 km to 12.5 km





End Game Minimum and Maximum Altitudes

Penumbral Lunar Eclipse

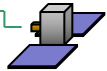
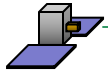




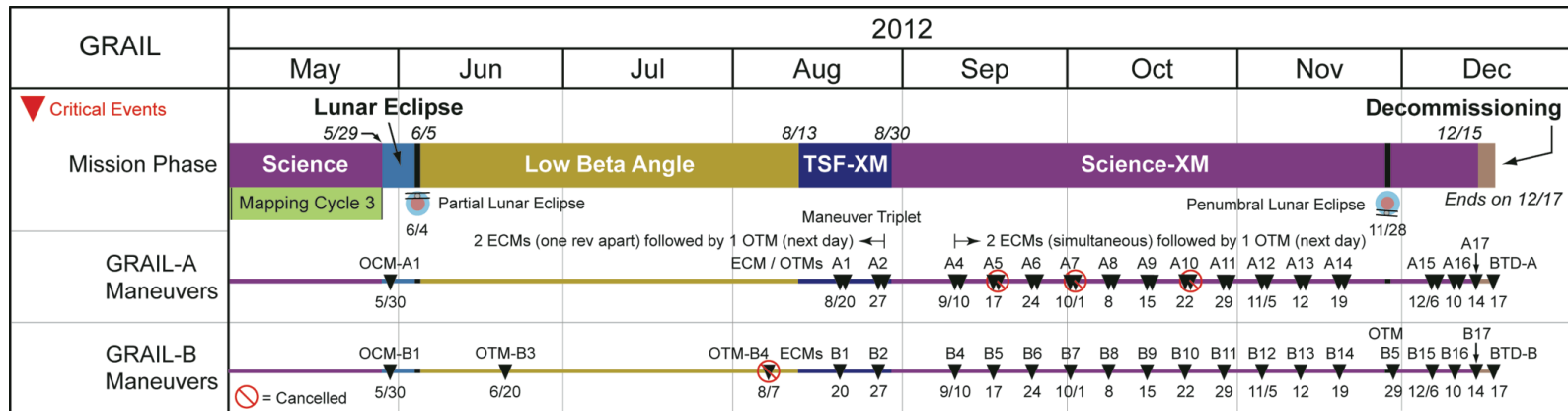
Extended Mission Maneuver Summary

(Including End Game)

GRAIL
Discovery

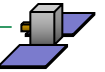
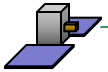


- Number of Maneuvers Performed: 50
 - GRAIL-A (Ebb): 30 (3 cancelled)
 - GRAIL-B (Flow): 20 (1 cancelled)



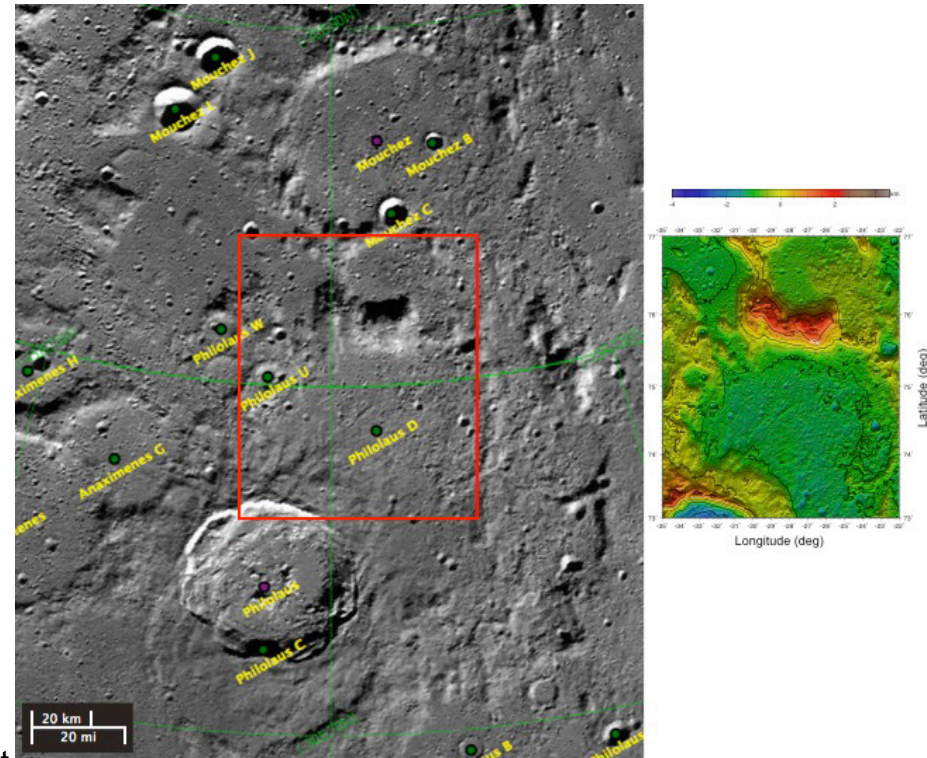
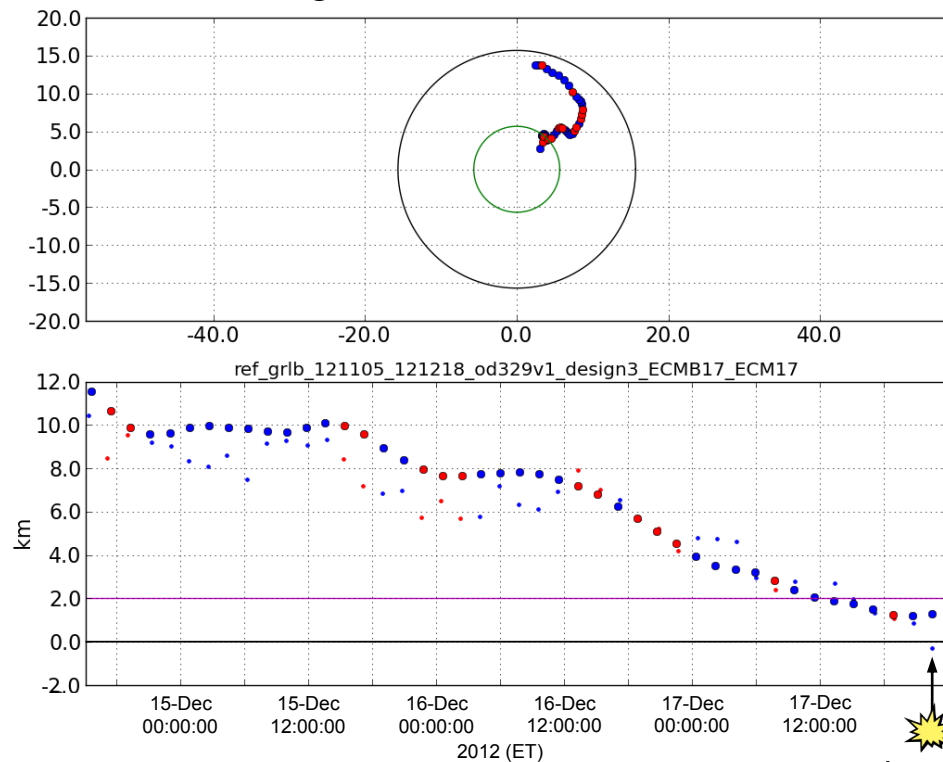
ECM-17 and
BTD Designs

- Maneuver Terminology
 - LEC Phase: OCMs (Orbit Circularization Maneuvers)
 - Multiple Phases: ECMs (Eccentricity Correction Maneuvers)
 - Multiple Phases: OTMs (Orbit Trim Maneuvers)
 - Decommissioning Phase: BTD (Burn-to-Depletion)

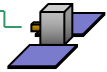
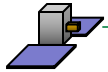


Maneuver Design Objectives

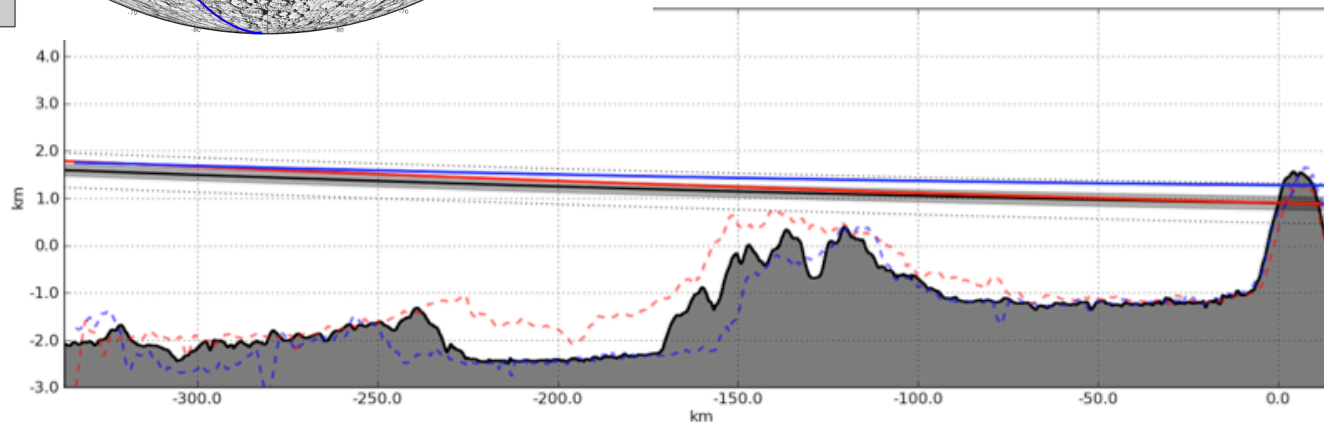
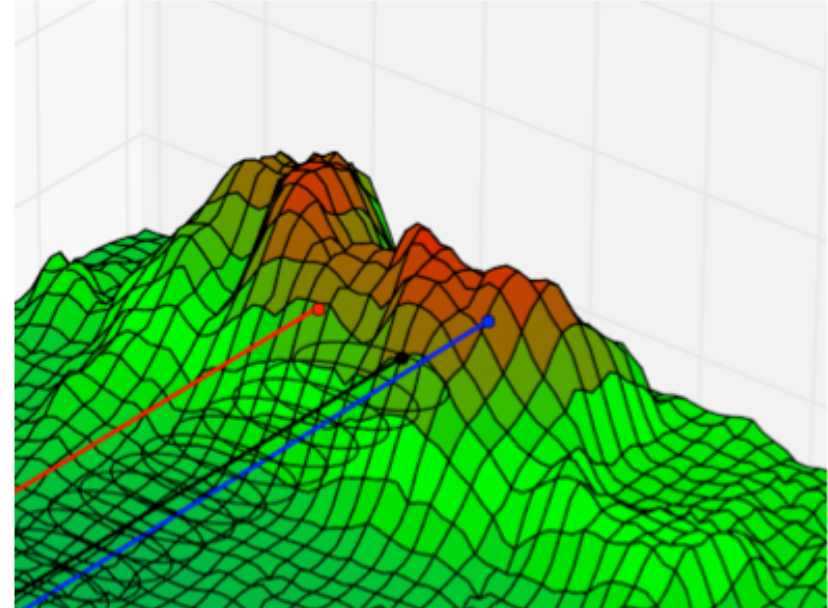
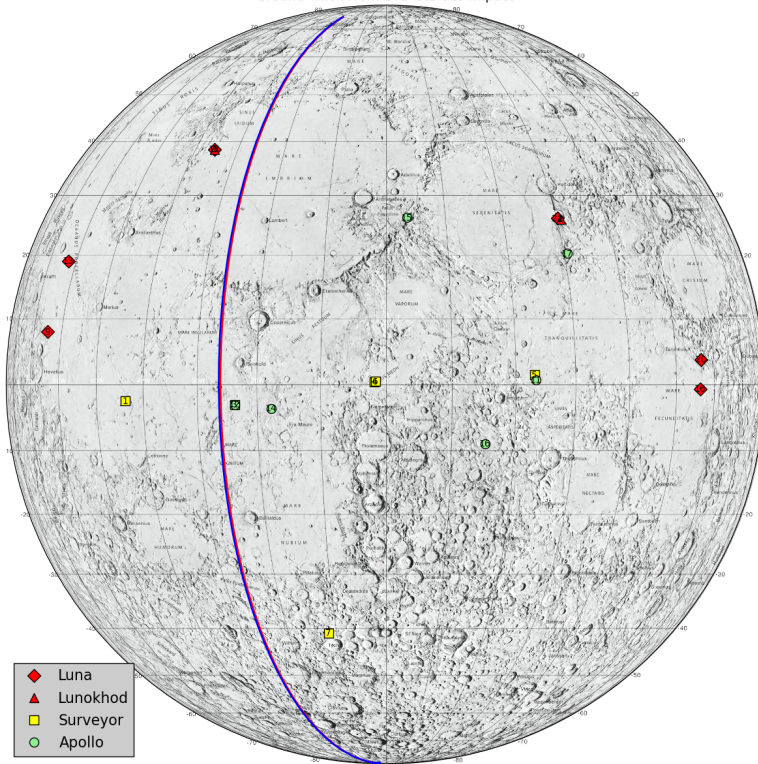
- Do not disturb Lunar Heritage Sites (the only hard “requirement”)
- Impact on the near side of the Moon (to be able to observe impact from Earth)
- Impact in the northern hemisphere (to be able to see execution of BTD maneuvers)
- Stay more than 2 km above lunar topography as long as possible
- Design was finalized on November 13th, just over a month from impact !



Targeting the Burn-to-Depletion Maneuver



Ground Track From BTM Start to Impact

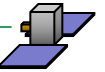
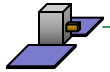




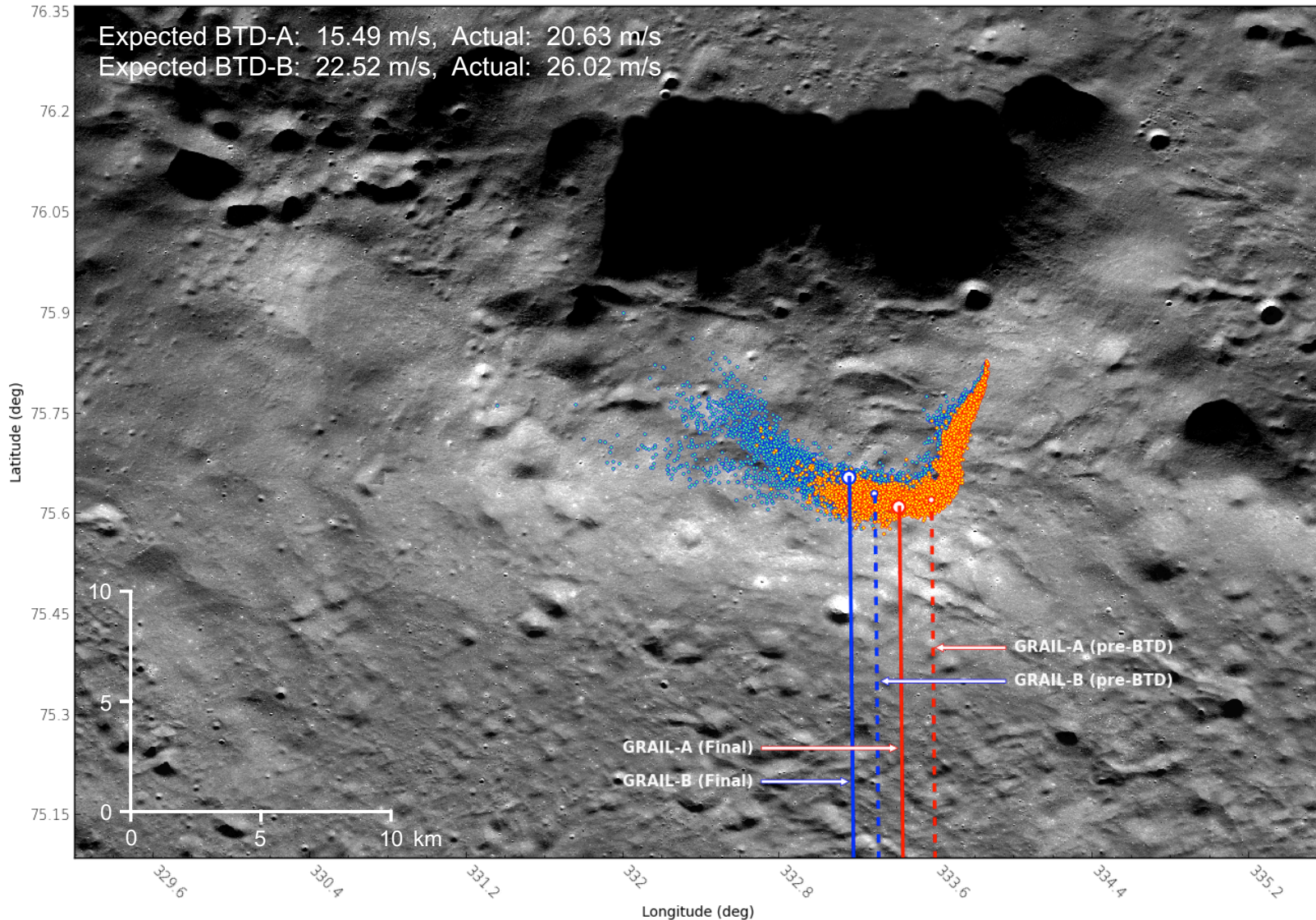
Comparison of pre- and post-BTD Trajectories

(10,000 sample BTD Monte Carlo)

GRAIL
Discovery



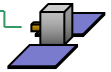
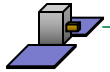
GRAIL End-of-Mission Impact





Final Orbits Prior to Impact

GRAIL
Discovery



GRAIL

- Animation from NASA/GSFC website: <http://svs.gsfc.nasa.gov/vis/a000000/a004000/a004023/>

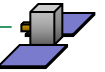
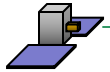
KARI-NASA KPLO F2F at JSC, November 19-21, 2019 – GRAIL Mission Overview

RBR-37



GRAIL Impact Locations Imaged by LRO

GRAIL
Discovery

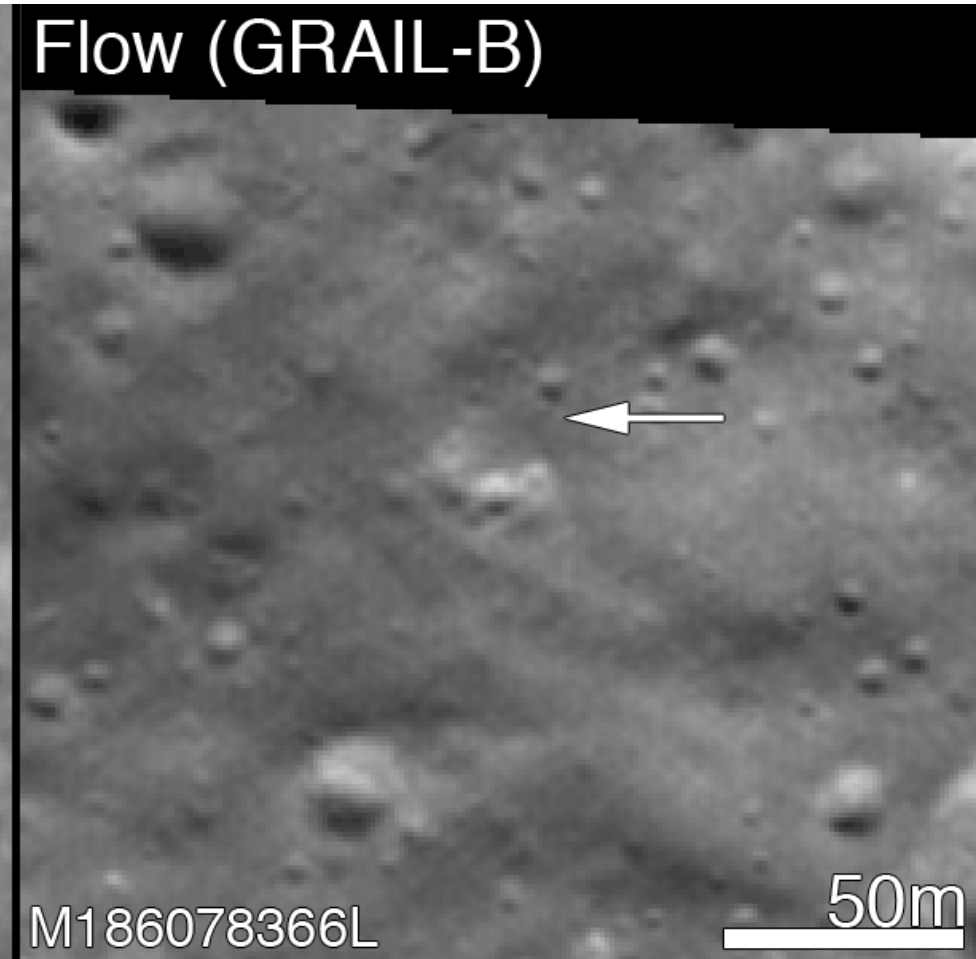


Ebb (GRAIL-A)



M186085512R

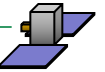
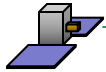
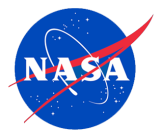
Flow (GRAIL-B)



M186078366L

50m

- Images from NASA/LRO website: http://www.nasa.gov/mission_pages/LRO/news/grail-results.html#.UwpHjSiFFpL

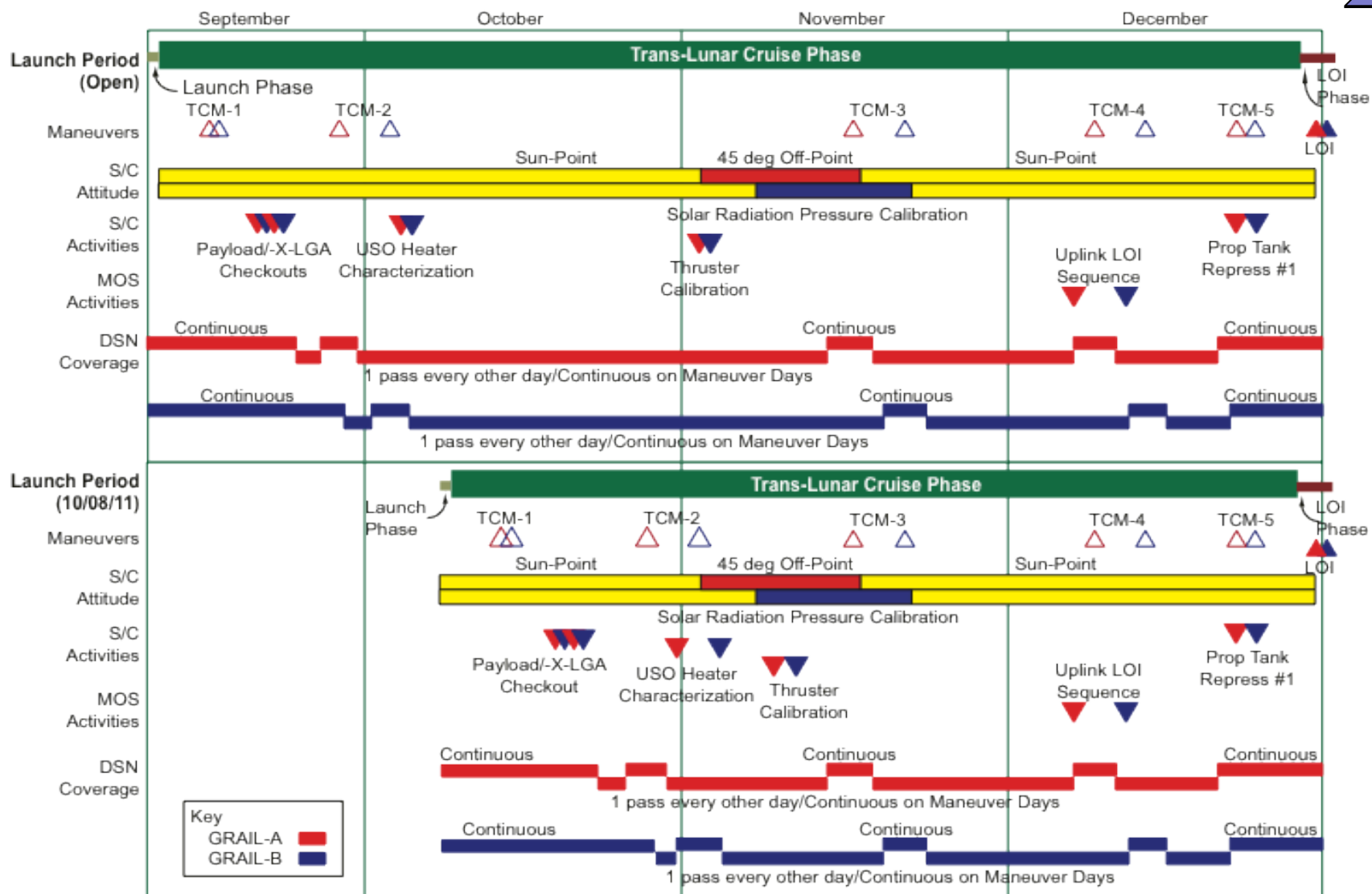


Mission and Navigation Operations



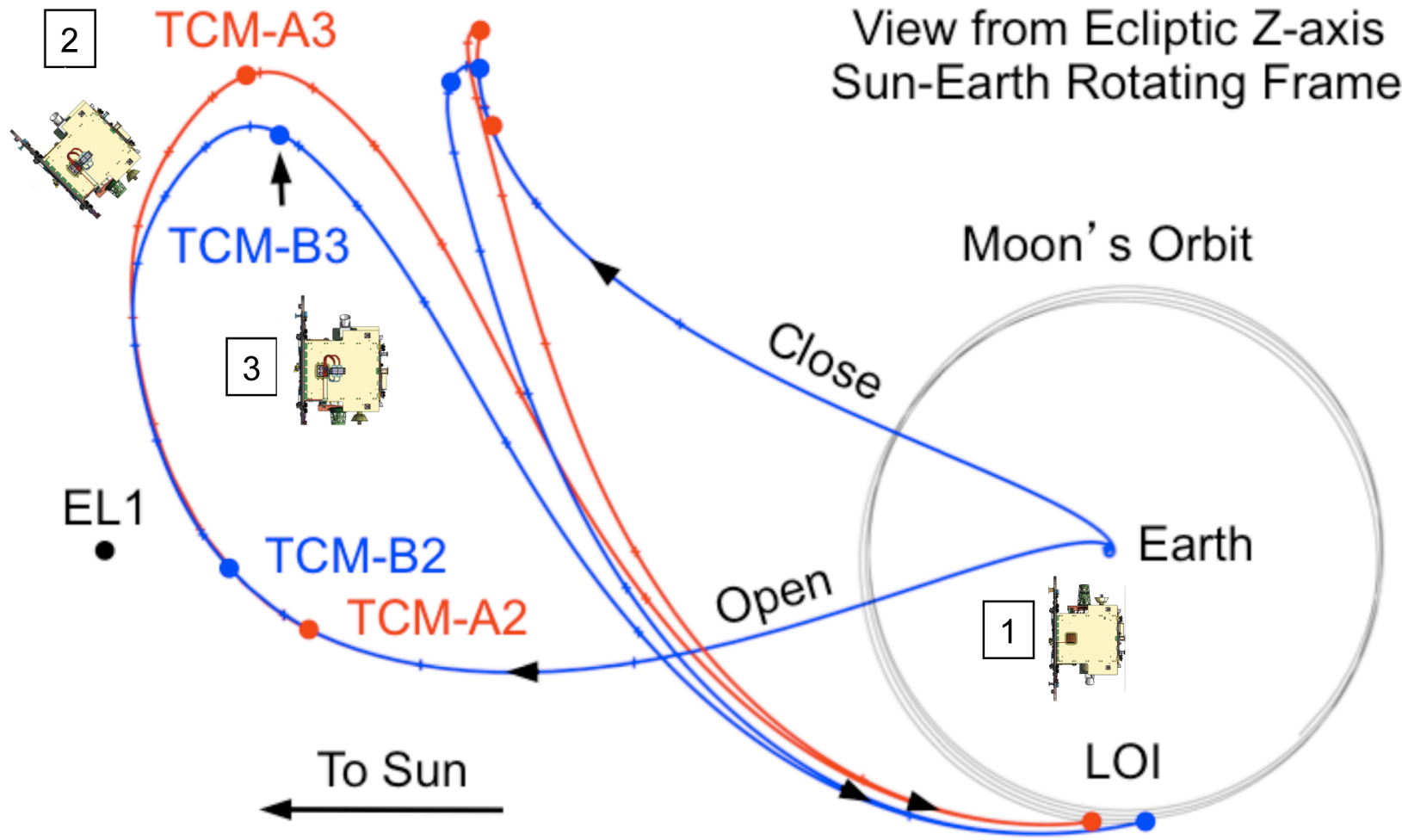
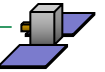
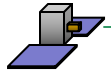
Trans-Lunar Cruise Phase Timeline

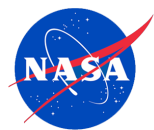
GRAIL
Discovery



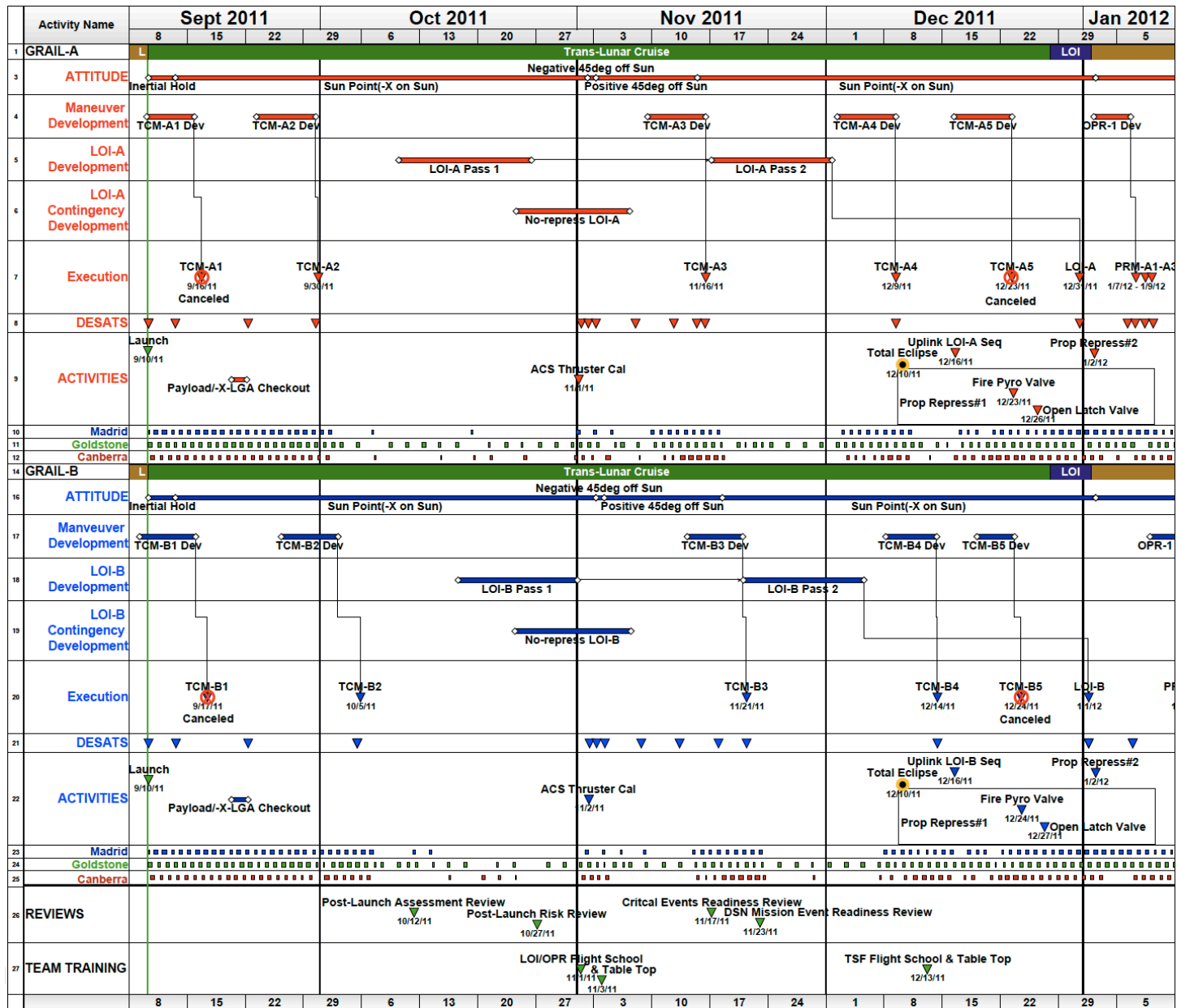


Spacecraft Attitude During TLC Phase



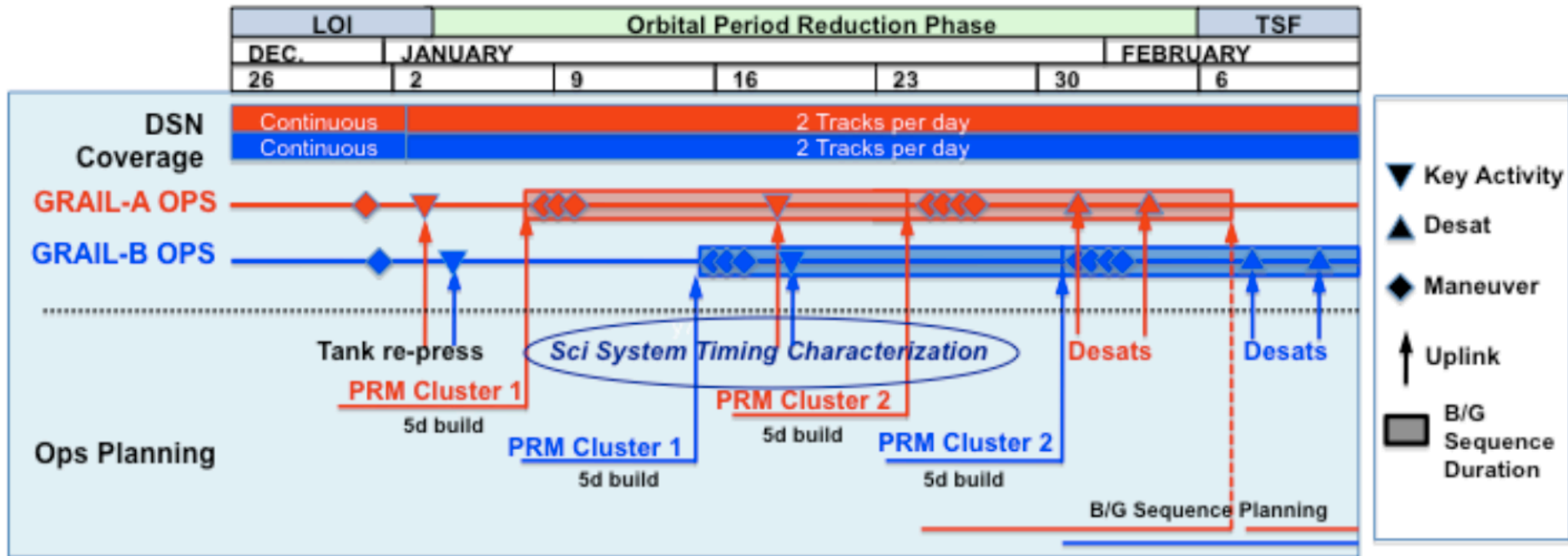
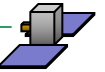
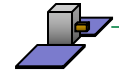


Maneuver Development Timeline in TLC Phase





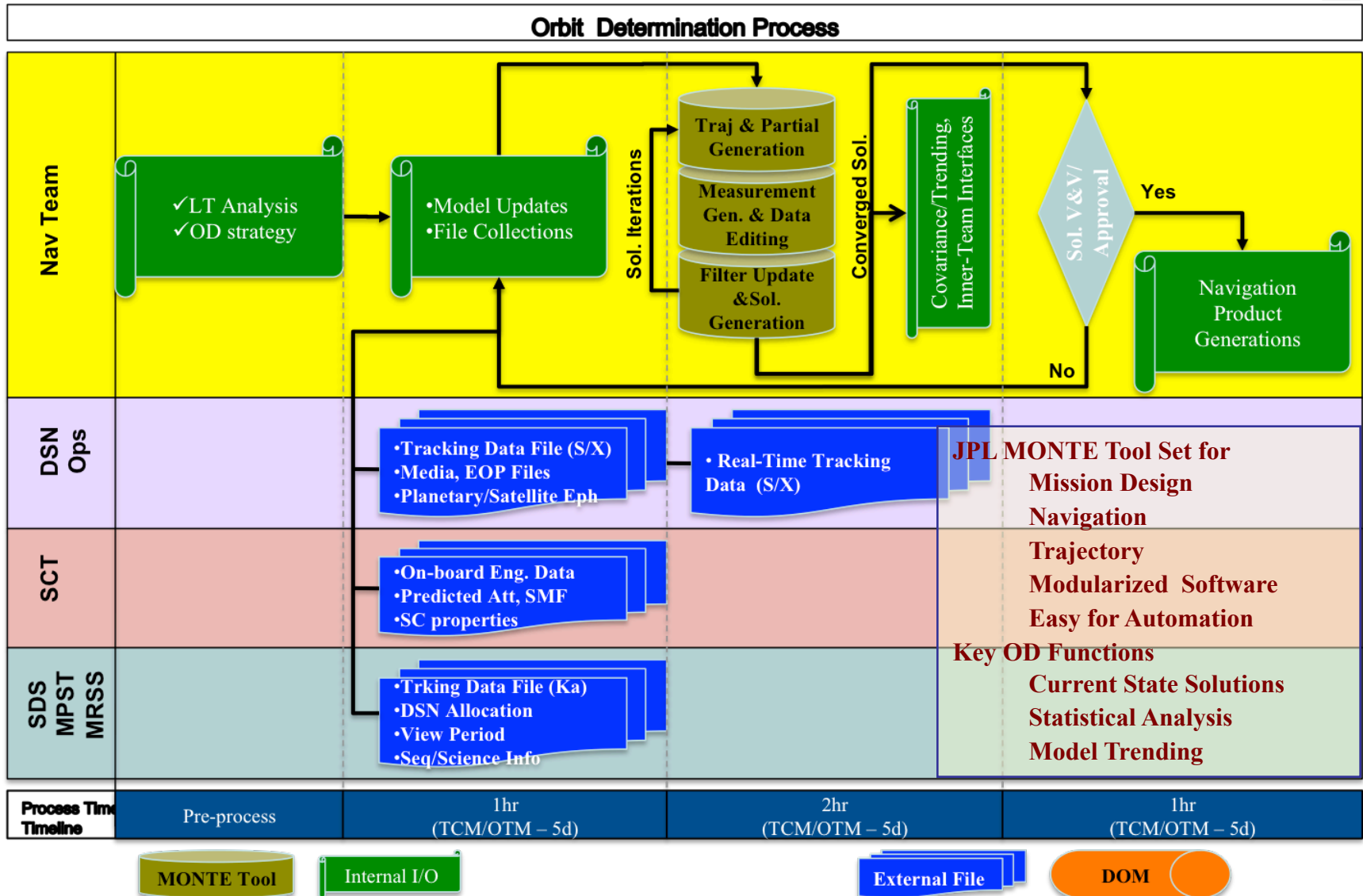
Maneuver Development Timeline in OPR Phase



- 7 Period Reduction Maneuvers (PRMs) per orbiter, divided into two clusters
- Reduced 11.5 hour orbit to less than 2 hours
- Utilized 5 day maneuver planning timeline
- Background (housekeeping) sequence merged with maneuver sequence

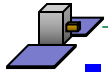


Orbit Determination Process

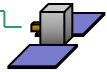




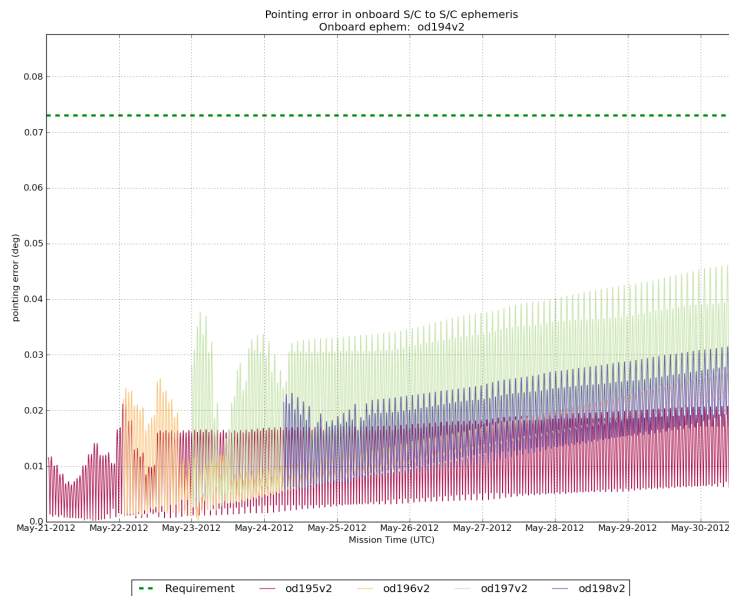
Orbit Determination Scenario in Lunar Orbit



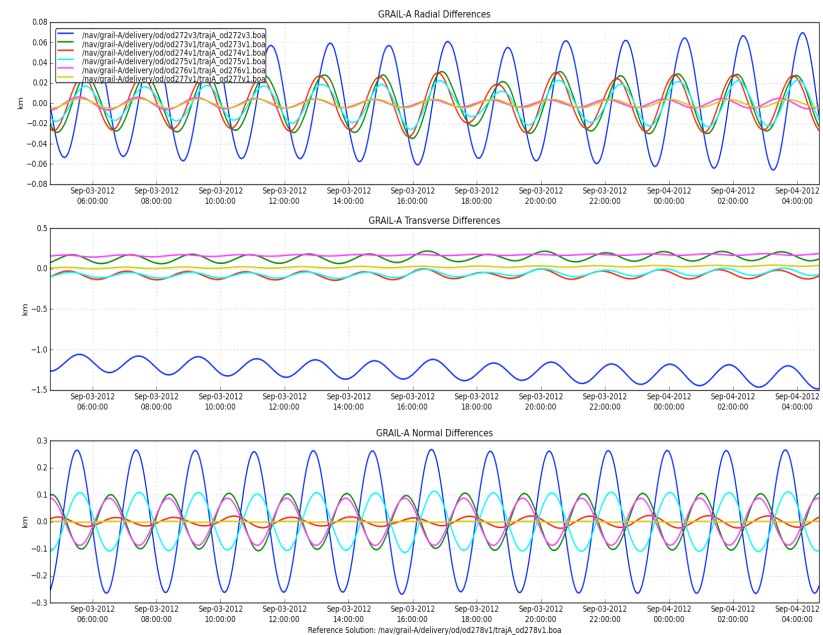
- Orbit determination frequency: 6-7 solutions per week
- Twice weekly delivery of predicted trajectories to project and DSN
- Monitor trajectory difference during solution overlap, long term trends in orbital elements, spacecraft-to-spacecraft pointing, predicted occultation entry/exit time, and predicted trajectory differences

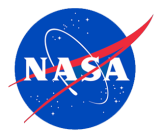


Spacecraft-to-Spacecraft Pointing

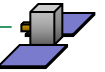
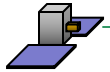


Predicted Trajectory Comparison



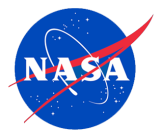


Gravity Modeling

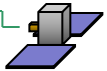
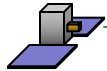


- Initial gravity model – LP150Q spherical harmonic field
 - Derived from ground based S-band Doppler tracking of Lunar Prospector
- Subsequent models – developed by the GRAIL Science Team
 - Based on GRAIL LGRS Ka-band spacecraft-to-spacecraft range rate data
 - Global coverage
 - Various degree and order expansions and truncations

| Date of First Use | Field ID | Truncation | Phase |
|-------------------|-------------|------------|---------------------|
| March 7, 2012 | lp150q | 150x150 | SCI |
| April 13, 2012 | grail270a9a | 200x200 | SCI, LEC, LBA |
| June 7, 2012 | grail360b6a | 200x200 | LBA |
| August 3, 2012 | grail420c1a | 200x200 | LBA, TSF-XM, SCI-XM |
| September 1, 2012 | grail420c1a | 300x300 | SCI-XM |
| October 26, 2012 | grail540c3a | 320x320 | SCI-XM |
| December 6, 2012 | grail660c5a | 400x400 | SCI-XM, DEC |

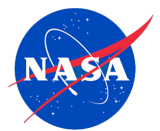


Orbit Determination Activities in SCI-XM Phase



| Orbit Determination Activities in Blue | | All Activities for Two Spacecraft Except for OTM Support (GRAIL-A Only) | | |
|---|---|---|--|----------------------------------|
| MONDAY | TUESDAY | WEDNESDAY | THURSDAY | FRIDAY |
| OD for Maneuver R/T Monitoring | OD for Maneuver R/T Monitoring | ECM Design Project Approval | | Sequence Timing Update if Needed |
| Maneuver R/T Monitor Setup | Maneuver R/T Monitor Setup | | | |
| ECM Maneuver | OTM Maneuver | Daily OD | Daily OD | Daily OD |
| R/T Monitoring Quick Assessment OD Reconstruction Product Delivery | R/T Monitoring Quick Assessment OD Reconstruction Product Delivery | Develop Staffing Plan, Tracking Data Delivery Schedule and OD Delivery Schedule for Next Week | ECM Covariance Analysis | |
| Weekend OD | Weekend OD | | | |
| OTM Design | ECM Design | | | ECM R/T Monitoring Prep |
| Trajectory Prediction with/without OTM | ECM Design Navigation Internal Approval | ECM Design Validation | Trajectory Prediction with/without ECM | |
| OTM R/T Monitoring Prep | | | | |

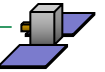
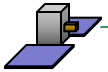
Note: Activity Durations Approximate



Contingency Planning during the TLC Phase

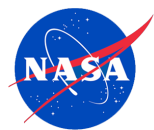


TCM Planning

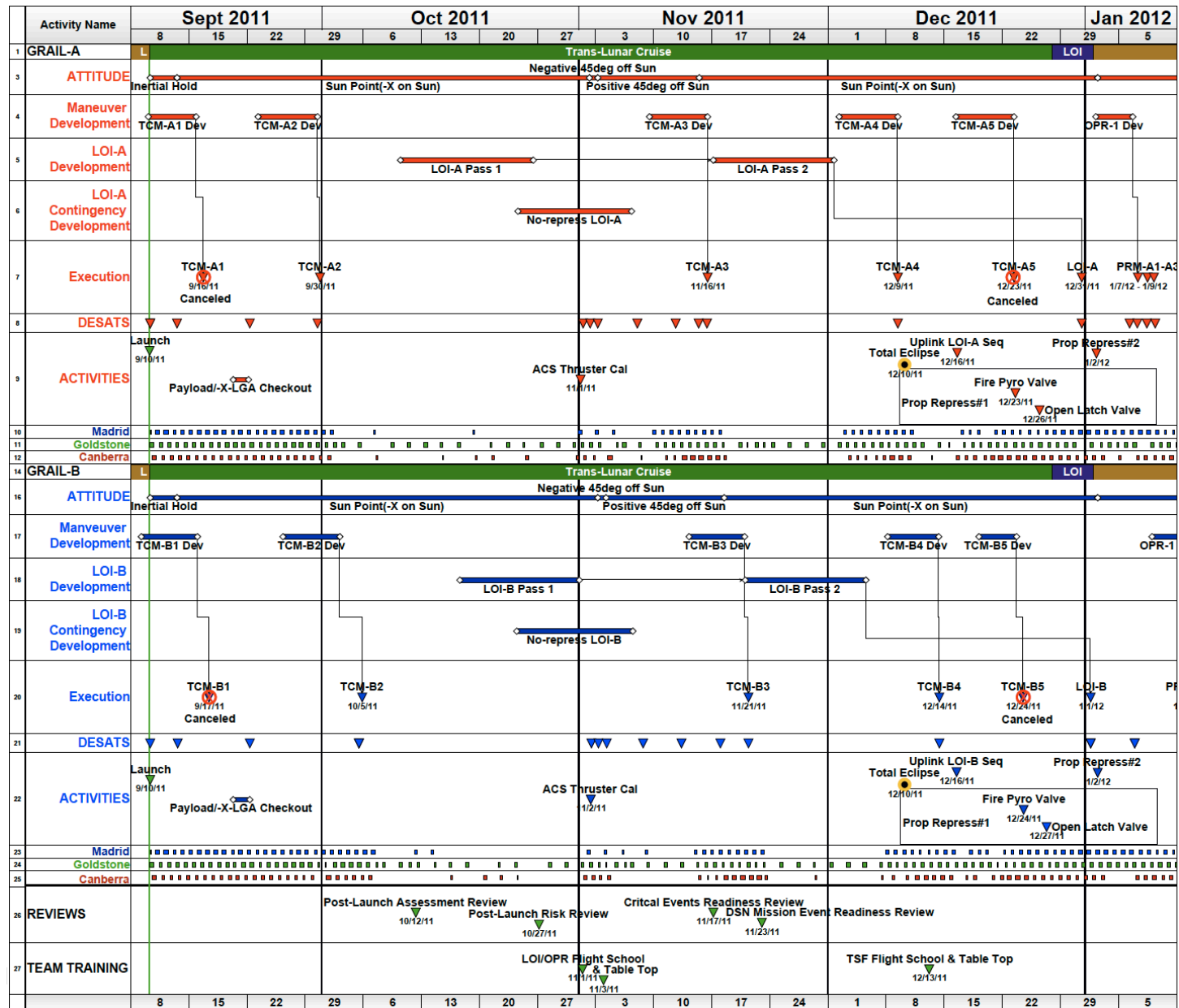


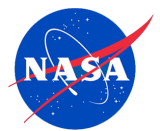
- Backup TCM Opportunities
 - Backup opportunities existed for all TCMs (on both GRAIL-A and GRAIL-B)
 - TCM-1: Backup scheduled (at least) 4 days after nominal
 - TCMs 2, 3, and 4: Backups scheduled one week after nominal TCM
 - TCM-5: Backup scheduled at LOI-3 days (nominal at LOI-8 days)

- Accommodating Launch Delays
 - TCM-1 and TCM-2 occur at a fixed time relative to launch
 - TCMs 3, 4, and 5 occur at a fixed time relative to LOI
 - TCMs 2 and 3 combined for launch dates “late” in the launch period due to shrinking TLC Phase timeline

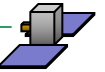
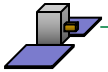


Maneuver Development Timeline in TLC Phase





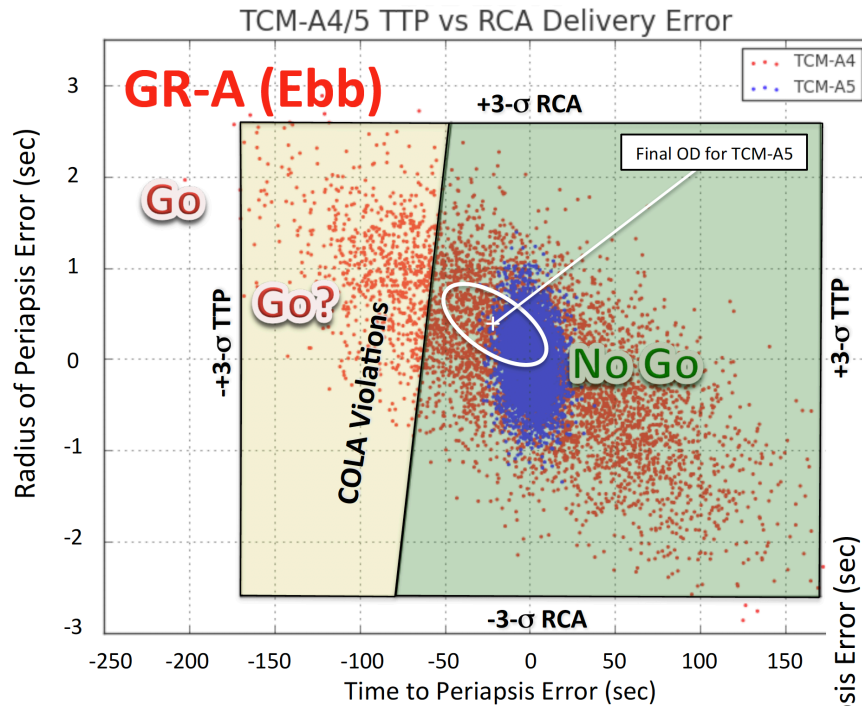
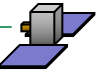
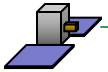
TCM-5 Planning



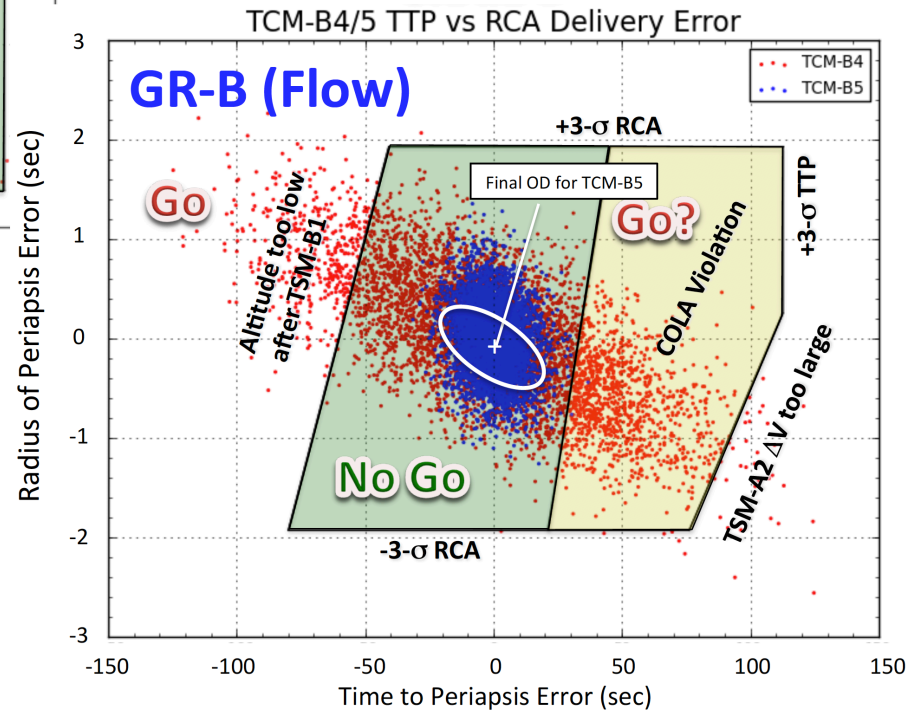
- To ensure that all the science requirements can be satisfied with TCM-5, must show $\pm 3\sigma$ TCM-5 values can be handled adequately
- To be able to cancel TCM-5, must show $\pm 3\sigma$ TCM-4 dispersions can be handled adequately — or, if some $\pm 3\sigma$ TCM-4 dispersions are too large, must establish some boundaries on those parameters
- Targeted LOI Parameters
 - SMA (semi-major axis), RCA (radius of closest approach), INC (inclination), LAN (longitude of the ascending node), AOP (argument of periapsis), TTP (time to periapsis)
 - The most critical delivery parameters were TTP and RCA
- Derived Requirements
 - Ensure no orbital crossing (i.e. COLA (collision avoidance) ≥ 10 km) while placing GRAIL-A and GRAIL-B into the science formation
 - LOI Phase: LOIs capture spacecraft into 11.5 hour orbits
 - OPR Phase: Two clusters of PRMs reduce periods to near science periods
 - TSF Phase: Max ΔV of each of the TSMs derived such that the execution error propagation does not exceed the expected limit for the formation

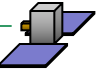
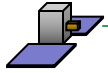


TCM-5 Go/No-Go Criteria



TCM-A5 canceled
TCM-B5 canceled





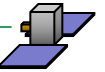
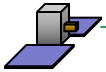
Backup Slides

- GRAIL References
- Trans-Lunar Cruise Trajectory Characteristics
- Maneuver Strategy for the Transition to Science Formation Phase
 - Establishing an Orbit Formation While Accommodating Maneuver Execution Errors



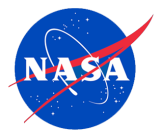
References

(the author list of the References is composed of the members of the GRAIL MDNAV Teams)



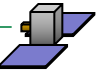
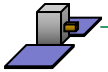
■ GRAIL Mission Design and Mission Operations Papers

- 2010 AIAA/AAS Astrodynamics Specialist Conference – August 2010, Toronto, Ontario, Canada
 - Roncoli, R. B., Fujii, K. K., “Mission Design Overview for the Gravity Recovery and Interior Laboratory (GRAIL) Mission”, *AIAA/AAS Astrodynamics Specialist Conference*, AIAA 2010-8383, Toronto, Ontario, Canada, August 2010.
 - Chung, M. J., Hatch, S. J., Kangas, J. A., Long, S. M., Roncoli, R. B., Sweetser, T. H., “Trans-Lunar Cruise Trajectory Design of GRAIL (Gravity Recovery and Interior Laboratory) Mission”, *AIAA/AAS Astrodynamics Specialist Conference*, AIAA 2010-8384, Toronto, Ontario, Canada, August 2010.
 - Hatch, S. J., Roncoli, R. B., Sweetser, T. H., “GRAIL Trajectory Design: Lunar Orbit Insertion through Science”, *AIAA/AAS Astrodynamics Specialist Conference*, AIAA 2010-8385, Toronto, Ontario, Canada, August 2010.
 - Sweetser, T. H., “How to Maneuver Around in Eccentricity Vector Space”, *AIAA/AAS Astrodynamics Specialist Conference*, AIAA 2010-7523, Toronto, Ontario, Canada, August 2010.
- 2012 AIAA/AAS Astrodynamics Specialist Conference – August 2012 – Minneapolis, MN, USA
 - Sweetser, T. H., Wallace, M. S., Hatch, S. J., Roncoli, R. B., “Design of an Extended Mission for GRAIL”, *AIAA/AAS Astrodynamics Specialist Conference*, AIAA 2012-4429, Minneapolis, Minnesota, August 2012.
 - Wallace, M. S., Sweetser, T. H., Roncoli, R. B., “Low Lunar Orbit Design via Graphical Manipulation of Eccentricity Vector Evolution”, *AIAA/AAS Astrodynamics Specialist Conference*, AIAA 2012-4748, Minneapolis, Minnesota, August 2012.
- 2014 AAS Guidance and Control Conference – February 2014 – Breckenridge, CO, USA
 - Wallace, M. S., Roncoli, R. B., Young, B. T., Hatch, S. J., “The Last Days of GRAIL”, *AAS Guidance and Control Conference*, AAS-14-127, Breckenridge, Colorado, February 2014.
- 2012 SpaceOps Conference – June 2012 – Stockholm, Sweden
 - Havens, G. G., Beerer, J. G., “Designing Mission Operations for the Gravity Recovery and Interior Laboratory Mission”, *2012 SpaceOps Conference*, Stockholm, Sweden, June 2012
 - Beerer, J. G., Havens, G. G., “Operating the Dual-Orbiter GRAIL Mission to Measure the Moon's Gravity”, *2012 SpaceOps Conference*, Stockholm, Sweden, June 2012



References

(the author list of the References is composed of the members of the GRAIL MDNAV Teams)



■ GRAIL Navigation Papers

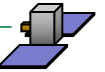
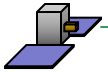
- 2012 23rd International Symposium on Space Flight Dynamics – October 2012 - Pasadena, CA, USA
 - Antreasian, P. G., Bhat, R. S., Broschart, S. B., Chung, M. J., Criddle, K. E., Goodson, T. D., Hatch, S. J., Jefferson, D. C., Lau, E. L., Mohan, S., Parker, J. S., Roncoli, R. B., Ryne, M. S., Sweetser, T. H., Young, B. T., “Navigation of the Twin GRAIL Spacecraft into Science Formation at the Moon”, *23rd International Symposium on Space Flight Dynamics (ISSFD)*, Pasadena, California, November 2012.
 - You, T., Antreasian, P., Broschart, S., Criddle, K., Higa, E., Jefferson, D., Lau, E., Mohan, S., Ryne, M., Keck M., “Gravity Recovery and Interior Laboratory Mission (GRAIL) Orbit Determination”, *23rd International Symposium on Space Flight Dynamics (ISSFD)*, Pasadena, California, November 2012.
- 2013 23rd AAS/AIAA Spaceflight Mechanics Meeting – February 2013 – Kauai, HI, USA
 - Ryne, M., Antreasian, P., Broschart, S., Criddle, K., Gustafson, E., Jefferson, D., Lau, E., Wen, H., You, T., “GRAIL Orbit Determination for the Science Phase and Extended Mission”, *23rd AAS/AIAA Space Flight Mechanics Meeting*, AAS-13-269, Kauai, Hawaii, February 2013.
 - Goodson, T. D., “Execution-Error Modeling and Analysis of the GRAIL Spacecraft Pair”, *23rd AAS/AIAA Space Flight Mechanics Meeting*, AAS-13-268, Kauai, Hawaii, February 2013.
- 2013 AIAA/AAS Astrodynamics Specialist Conference – August 2013 – Hilton Head, SC, USA
 - Chung, M. J., “GRAIL TCM-5 Go/No-Go: Developing Lunar Orbit Insertion Criteria”, *AAS/AIAA Astrodynamics Specialist Conference*, AAS-13-712, Hilton Head, South Carolina, August 2013.
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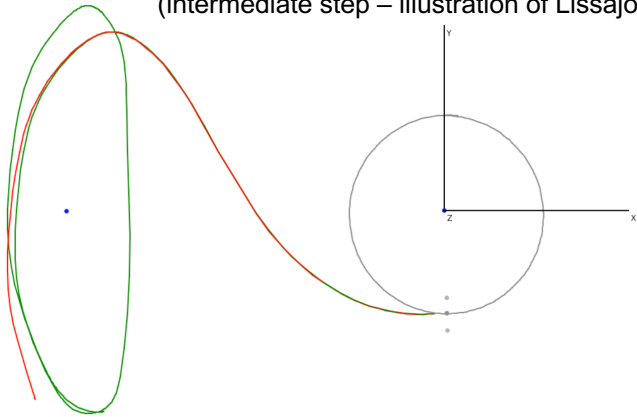
TLC Trajectory Design

[Snapshots of the Trajectory Design Process Illustrated in the Video Clip presented earlier]

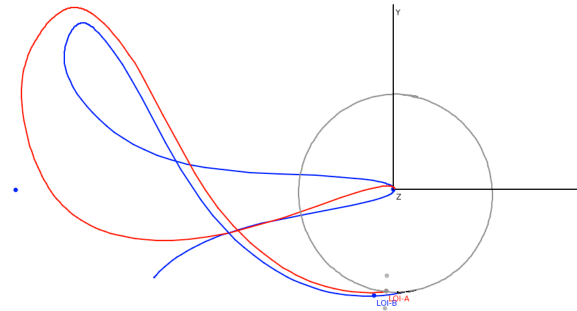
GRAIL
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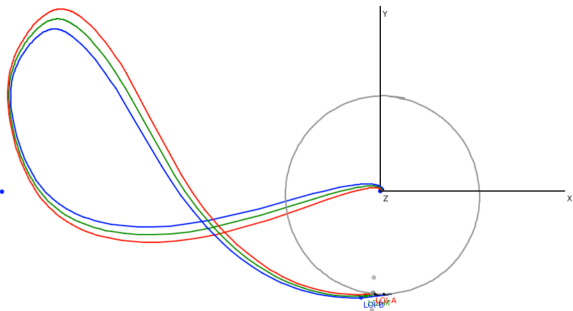
Backwards propagation of GRAIL-A trajectory from the Moon
(intermediate step – illustration of Lissajous orbit)



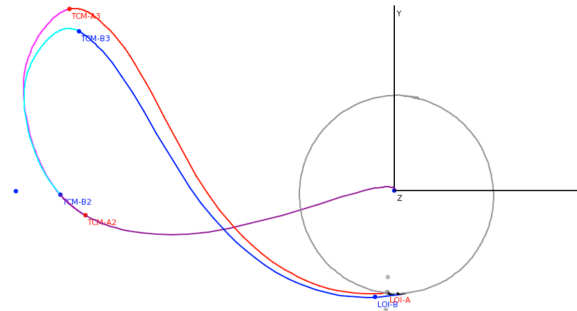
Backwards propagation of GRAIL-B trajectory from the Moon
(GRAIL-B intermediate step – GRAIL-A done)



Backwards propagation of “common” (middle) trajectory from the Moon



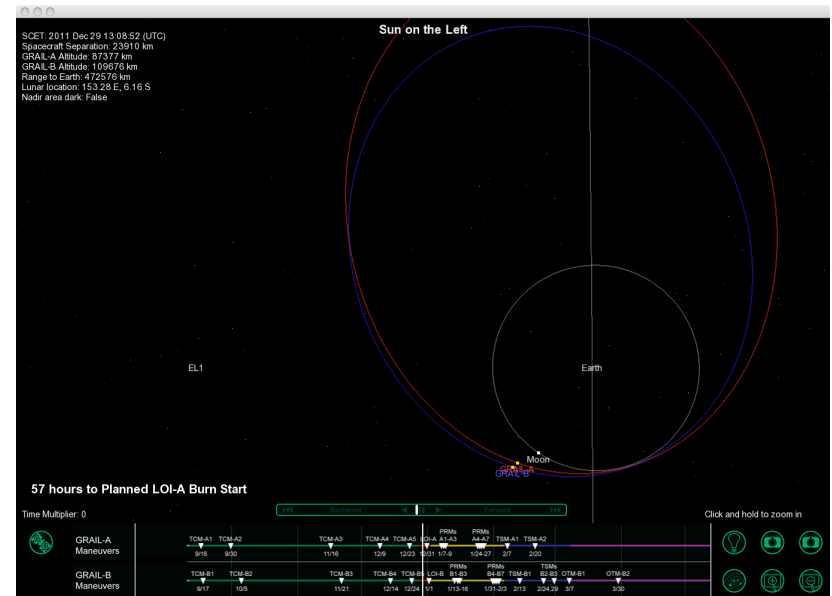
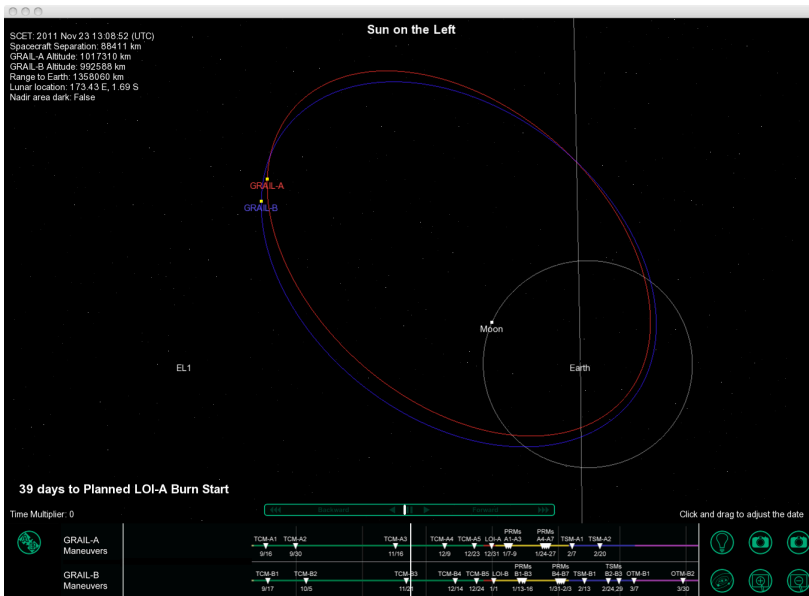
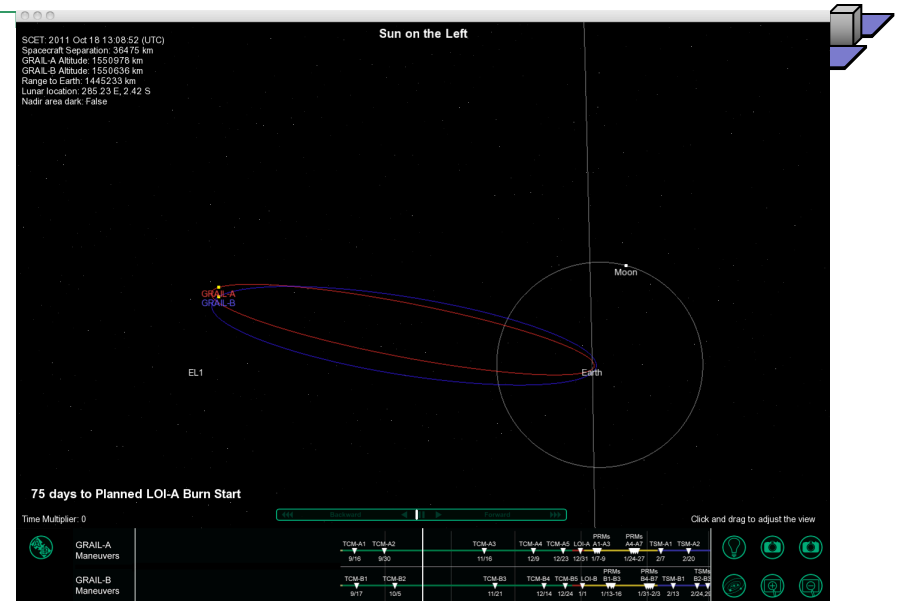
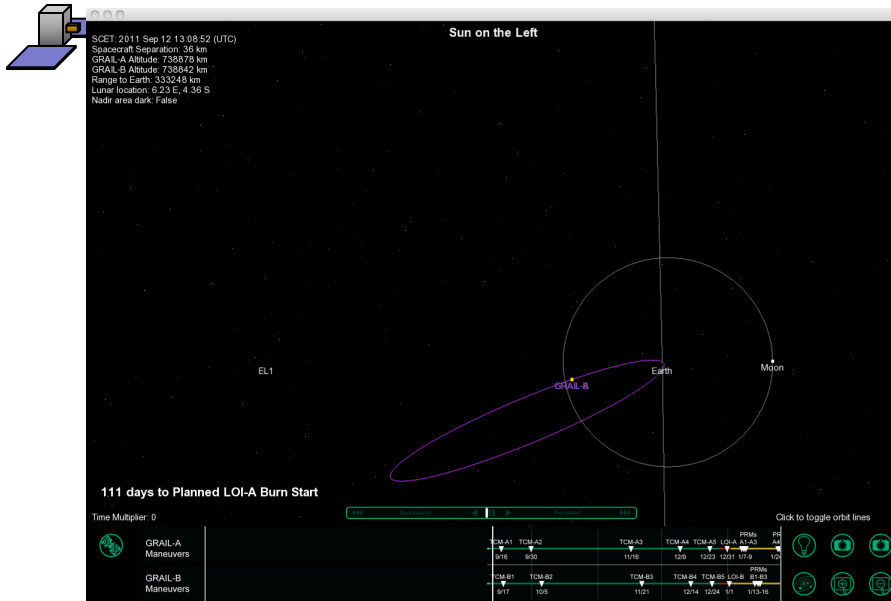
Final converged common launch trajectory inserted into backwards propagated trajectories via two TCMs – optimized to minimize total ΔV

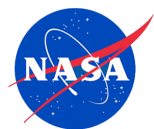




Visualization of TLC Trajectory

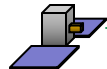
[Snapshots of the Change in Two-Body Ellipse Illustrated in the Video Clip presented earlier]



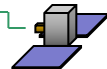
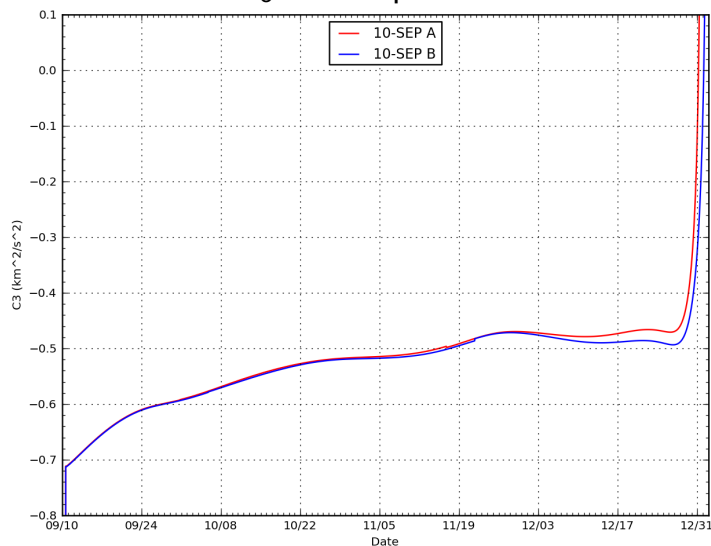


Trans-Lunar Cruise “Two-Body Energies”

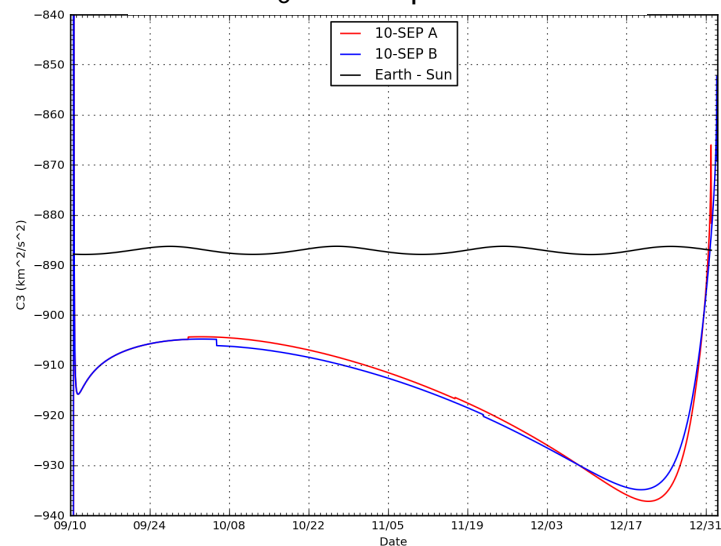
GRAIL
Discovery



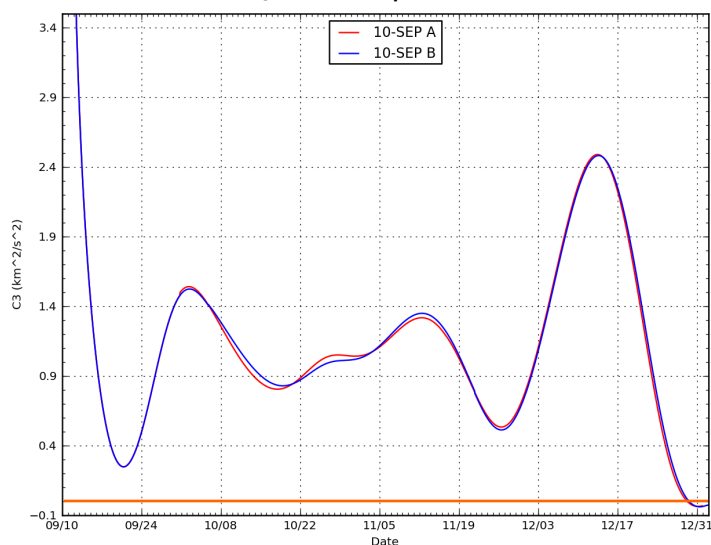
GRAIL C_3 with respect to the Earth



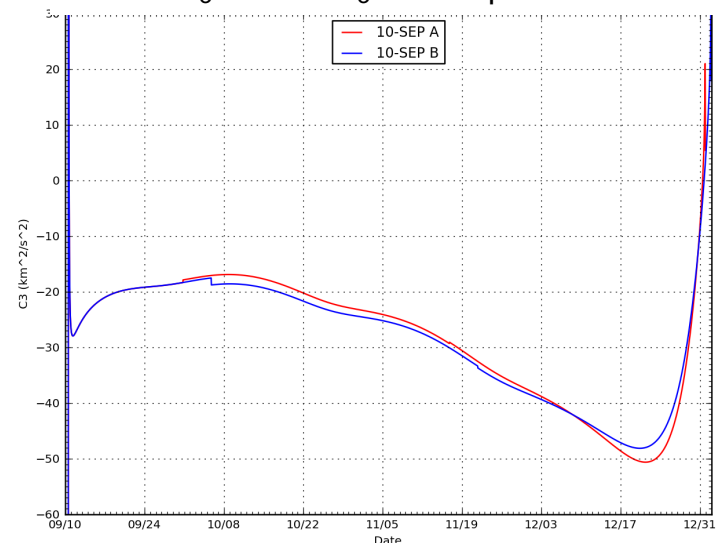
GRAIL C_3 with respect to the Sun



GRAIL C_3 with respect to the Moon

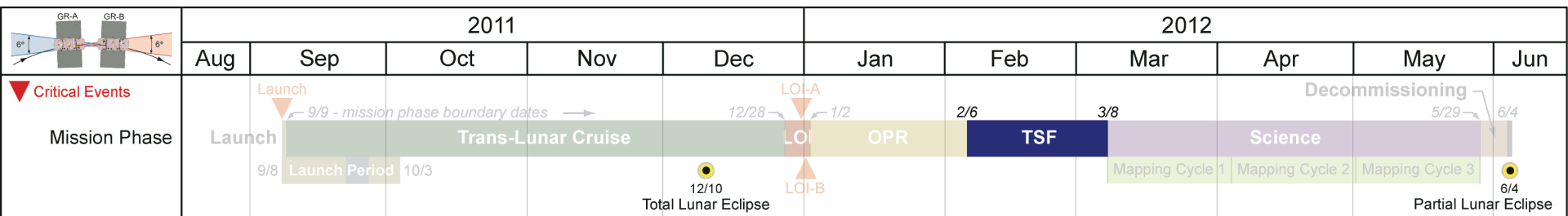
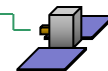
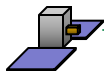


GRAIL C_3 – Earth C_3 with respect to the Sun





Transition to Science Formation Phase

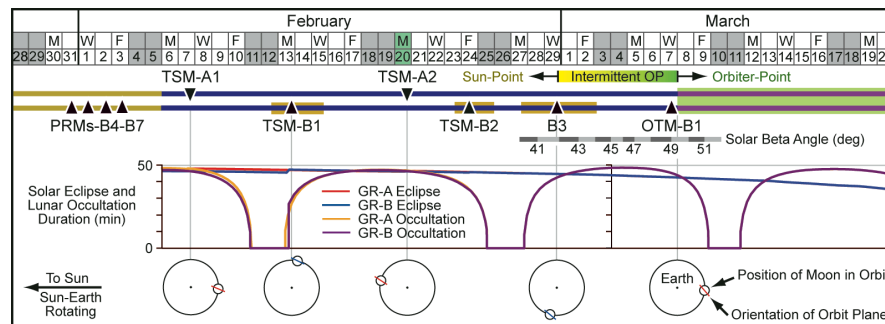


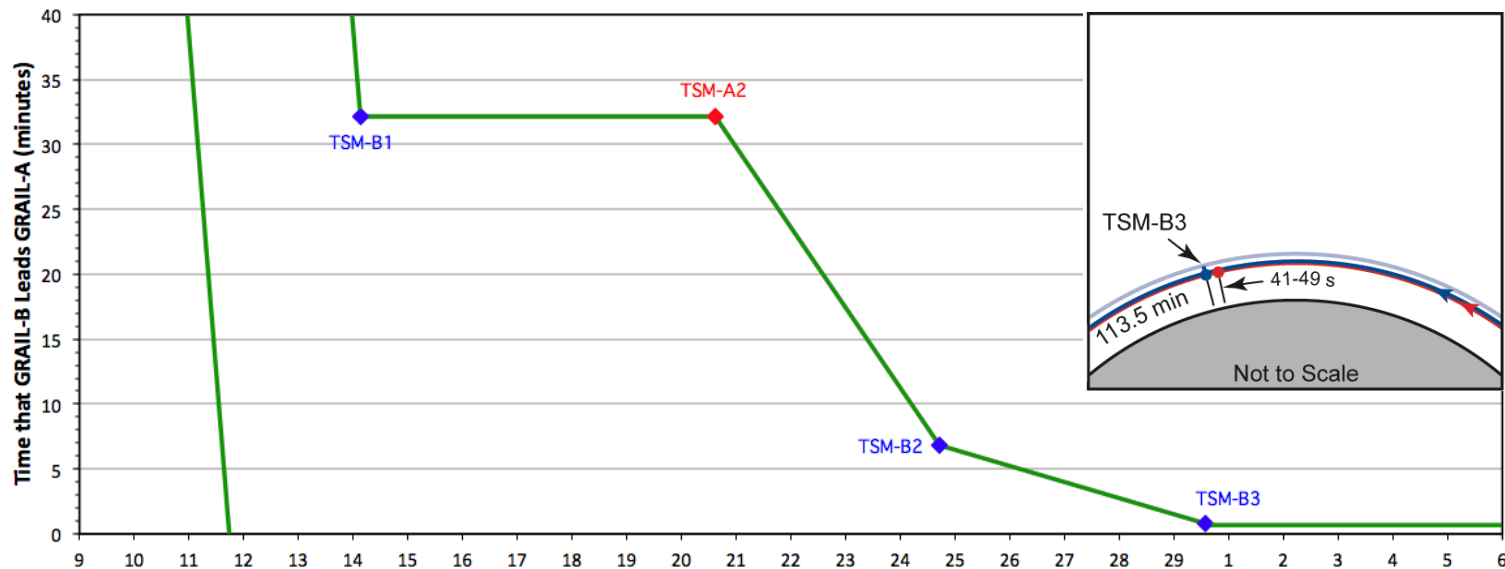
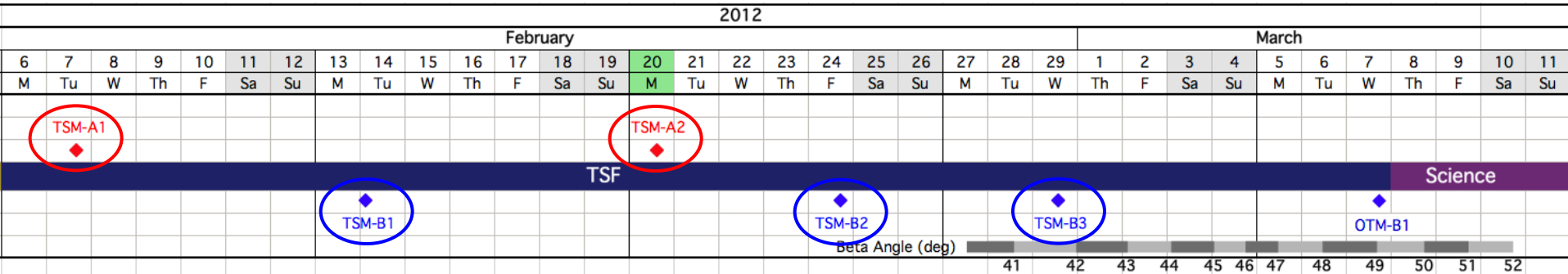
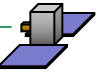
Objective of the TSF Phase

- To maneuver the two GRAIL orbiters from randomly phased initial conditions into a coordinated formation in the desired science orbit
- To test and calibrate the payload prior to the start of the Science Phase

Key Design Features

- Until this point in the mission, the orbiters had been independently operated – essentially flying two separate missions
- Five deterministic maneuvers were used to establish the proper formation at the start of the Science Phase
- The TSF strategy was designed to
 - Avoid a collision by controlling the phasing of the two orbiters
 - Accommodate variations caused by maneuver execution errors







Impact of Execution Errors on Maneuver Timing

GRAIL
Discovery

